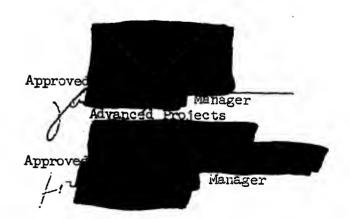


CORONA J PERFORMANCE EVALUATION REPORT MISSION 1044-1 and 1044-2 FTV 1639, J-41

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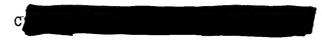


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INTRODUCTION

This report presents the final performance evaluation of Missions 1044-1 and 1044-2 of the Corona Program. The purpose of this report is to define the performance characteristics of the J-41 payload system and to identify the source of in-flight anomalies.

The performance evaluation was jointly conducted by representatives of Lockheed Missiles and Space Company (IMSC) and ITEK at the facilities of NPIC and AFSPPF. The off-line evaluation using Corona engineering photography acquired over the United States was performed at the individual contractors plants.

The quantitative data used for this report is obtained from government organizations. The diffuse density data, and MTF/AIM resolution are produced by AFSPPF. The vehicle attitude error values, frame correlation times are made at NPIC who also supply the Processing Summary reports published by

Computer programs developed by A/P are utilized to calculate and plot the frequency distribution of the various contributors to image smear to permit analysis and correlation of the conditions of photography to the information content and quality of the acquired pictures. Computer analysis of the exposure, processing and illumination data provides the necessary data to analyze the exposure criteria selected for the mission.

This report contains certain data summarized from Processing Summary, and from AFSPPF TERO Report;

SECTION 1

SYSTEM PERFORMANCE

A. MISSION OBJECTIVES

The payload section of Mission 1044, placed into orbit by Flight Test Vehicle #1639 and THORAD Booster #513, consisted of two panoramic cameras, two Stellar-Index cameras, two Mark 5A recovery capsules and a space structure to enclose the cameras and provide mounting surfaces for all equipment. Figure 1-1 presents an inboard profile of the J-41 payload system. This Corona "J" system is designed to acquire search and reconnaissance photography of selected areas of the earth from orbital altitudes. A seven day -1 mission and a seven day -2 mission was planned.

B. MISSION DESCRIPTION

The payload was launched from Vandenberg Air Force Base (VAFB) at 2131:19Z(1331:19 PST) on 2 November 1967. Ascent and injection were normal and the achieved orbit was within nominal tolerances. Tracking and command support was effected by the Air Force Satellite Control Facility consisting of tracking and command stations at

central control of the Satellite Test Center at Sunnyvale, California. Mission 1044-1 consisted of a 6 day operation and was completed by air recovery on 8 November 1967. Mission 1044-2 was completed with an air recovery on 11 November 1967 following a 3 day photographic operation. The very short -2 mission was precipitated by a potential failure in the lifeboat system.

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The comparison of the planned and actual orbit parameters is tabulated as follows:

ORBITAL PARAMETERS

Parameter	Predicted	Orbit 110 Actuals
Period (Min.)	90.147	90•333
Perigee (N.M.)	99.876	99•531
Apogee (N.M.)	223.750	219.940
Inclination (Deg.)	81.5	81.539
Perigee Latitude (Deg. N.)	19.24	33.816
Eccentricity	0.017191	0.01673

A single OAS rocket was fired on Rev 4, Rev 17, and Rev 113. These rocket firings produced the following results:

OAS ROCKET PERFORMANCE

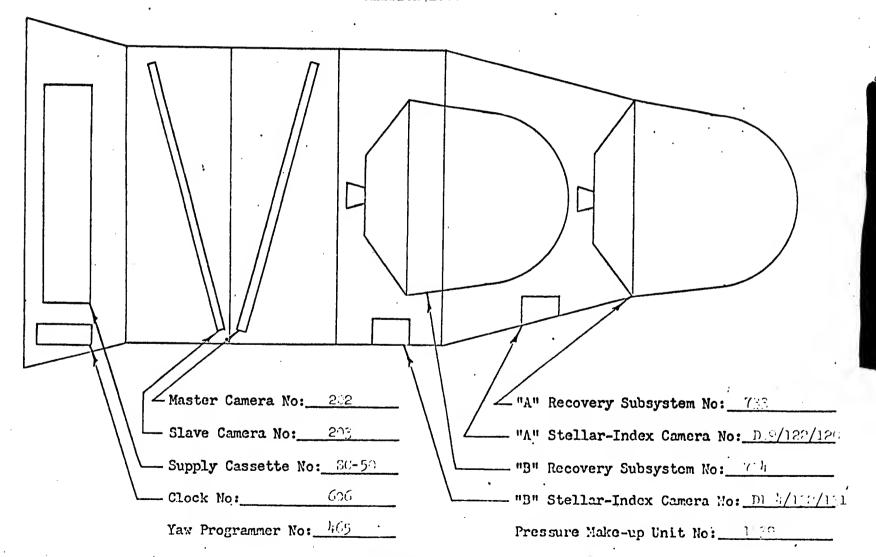
OAS Rocket	Velocity Gained
<i>⋕</i> ⊥	+ 16.2 FPS
# 2	+ 15.7 FPS
# 3	+ 17.5 FPS

C. PANORAMIC CAMERAS

Both instruments operated satisfactorily throughout both missions, and produced good image quality except for minor bands of image smearing near the takeup and on many frames. The imagery was very sharp, and verified the validity of the new focus settings.

SCHEMATIC INBOARD PROFILE - CORONA J-41 SYSTEM

MISSION 10/14



D. STELLAR-INDEX CAMERAS

Both the "A" and "B" S/I's operated satisfactorily and most Stellar images appear as points rather than the usual odd shaped stars.

E. OTHER SUB-SYSTEMS

The clock, instrumentation, pressure make-up, command and thermal control subsystems performed satisfactorily.

F. COMPONENT IDENTIFICATIONS AND SETTINGS

1. MASTER PANORAMIC CAMERA

COMPONENT ASSIGNMENT

Component	Serial Number
Main Camera	202
Main Camera Lens	2042435
Supply Horizon Camera	308-G6
Supply Horizon Camera Lens	12889
Take-up Horizon Camera	318-G5
Take-up Horizon Camera Lens	12886
Supply Cassette	SC-50

b. CAMERA DATA AND FLIGHT SETTINGS

Main Camera:

Lens	24"f/3.5
Slit Width	0.225"
Filter Type	Wratten 23A
Film Type	Eastman Type 3404

Supply (Port) Horizon Camera:

Lens 55 mm f/6.3

Aperture Setting f/6.3

Exposure Time 1/100 second

Filter Type Wratten 25

Take-up (Starboard) Horizon Camera:

Lens 55 mm f/6.3

Aperture Setting f/8.0

Exposure Time 1/100 second

Filter Type Wratten 25

2. SLAVE PANORAMIC CAMERA

a. COMPONENT ASSIGNMENT

Component	Serial Number
Main Camera	203
Main Camera Lens	2162435
Supply Horizon Camera	299-G6
Supply Horizon Camera Lens	12903
Take-up Horizon Camera	297-G5
Take-up Horizon Camera Lens	12883
Supply Cassette	SC-50

b. CAMERA DATA AND FLIGHT SETTINGS

Main Camera:

Lens 24"f/3.5

Slit Width 0.175"

Filter Type Wratten 21

Film Type Eastman Type 3404

Supply (Starboard) Horizon Camera:

Lens 55 mm f/6.3

Aperture Setting f/8.0

Exposure Time 1/100 second

Filter Type Wratten 25

Take-up (Port) Horizon Camera:

Lens 55 mm f/6.3

Aperture Setting f/6.3

Exposure Time 1/100 second

Filter Type Wratten 25

3. MISSION 1044-1 STELLAR-INDEX CAMERA

a. COMPONENT ASSIGNMENT

Component	Serial Number
Camera	D- 99
Index Reseau	122
Stellar Reseau	120

b. CAMERA DATA AND FLIGHT SETTINGS

Stellar Camera:

Lens 85 mm f/1.8

Exposure Time 1 second

Filter Type None

Film Type Eastman Type 3401

Index Camera:

Lens 38 mm f/4.5

Exposure Time 1/500 second

Filter Type Wratten 21

Film Type Fastman Type 3400

C

4. MISSION 1044-2 STELLAR-INDEX CAMERA

a. COMPONENT ASSIGNMENT

Component	Serial Number
Camera	D-104
Index Reseau	132
Stellar Reseau	131

b. CAMERA DATA AND FLIGHT SETTINGS

Stellar Camera:

Lens 85 mm f/1.8

Exposure Time 1 second

Filter Type None

Film Type Eastman Type 3401

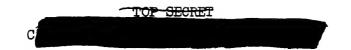
Index Camera:

Lens 38 mm f/4.5

Exposure Time 1/500 second

Filter Type Wratten 21

Film Type Eastman Type 3400



SECTION 2

PRE-FLIGHT SYSTE'S TESTS

As a standard procedure, the J payload systems are subjected to a series of tests which demonstrates a satisfactory level of confidence that the systems will indeed perform as required in their respective missions. The tests include and operational-type exposure to simulate thermal/altitude environment, a light-leak evaluation, and a dynamic measure of the photographic performance capabilities. Significant baseline levels and anomalies experienced with this system during the pre-flight testing are as follows:

A. ENVIRONMENTAL TEST

The J-41 payload system was subjected to an environmental HIVOS Chamber test from August 15 through August 19, 1966, and from August 27 through September 1, 1966. The interruption was caused by the actuation of a camera failsafe control during the cut and wrap sequence.

Except for some minor acceptable corona marking, the panoramic instruments performed satisfactorily. The Master camera failsafe was activated at the cut and wrap sequence when the film jammed in the felt seal preventing take-up into the "B" SRV. The failure was attributed to a combination of a misaligned "B" take-up cassette, and the vertical attitude of the camera system during the sequence which permitted the cut film to fall back and jam in the felt door opening.

The clock accuracy was satisfactory, except for one correlation that was outside of the accepted tolerance range.

The pressure make-up system operated normally. During PMU operate, internal pressure increased to 37-39 microns. Gas consumption was as high as 7.45 lbs/min. during -2 portion of the test.

TOP SECRETA

The command system functioned properly for both bucket tests with no evidence of any equipment malfunctions.

B. RESOLUTION TEST

Initial resolution and theodolite tests were performed on 20 September 1966. Results of the thru-focus resolution tests of pan instruments 202 and 203 show the following characteristics:

Master Pan Instrument No. 202

Maximum high contrast resolution 175 lines/mm at -0.002 focal position.

Maximum low contrast resolution 115 lines/mm at -0.002 focal position

Slave Instrument No. 203

Maximum high contrast resolution 176 lines/mm at +0.001 focal position.

Maximum low contrast resolution 112 lines/mm at +0.001 focal position.

Additional Boston investigations indicated that optimum focus position would be attained by adding 0.002" shim to the scan head of the Slave instrument, and 0.001" shim to the Master instrument. The modified instruments were retested 22 October 1967, with the following results:

Master Pan Instrument No. 202

Maximum high contrast resolution 183 lines/mm at -0.0025 focal position.

Maximum low contrast resolution 120 lines/mm at -0.0020 focal position.

Slave Pan Instrument No. 203

Maximum high contrast resolution 185 lines/mm at -0.0015 focal position.

Maximum low contrast resolution 118 lines/mm at -0.0020 focal position.

The final test data for both instruments is shown in Figures 2-1 and 2-2. Both instruments met the system requirements specification.

PRE-FLIGHT DYNAMIC RESOLUTION 300 200 Camera No: 202 (Lines per Millimeter) 150 Payload No: J-41 Resolution (1/mm) High Contrast: 183 100 90 80 Low Contrast: 120 PHOTOGRAPHIC ASSOLUTION 70 Film Typo: 3404 60 Test Date: 22 Oct. 1967 50 40 30

THROUGH FOCUS INCREMENTS (Inches)

0.000

20

-0.005

-0.004

-0.002

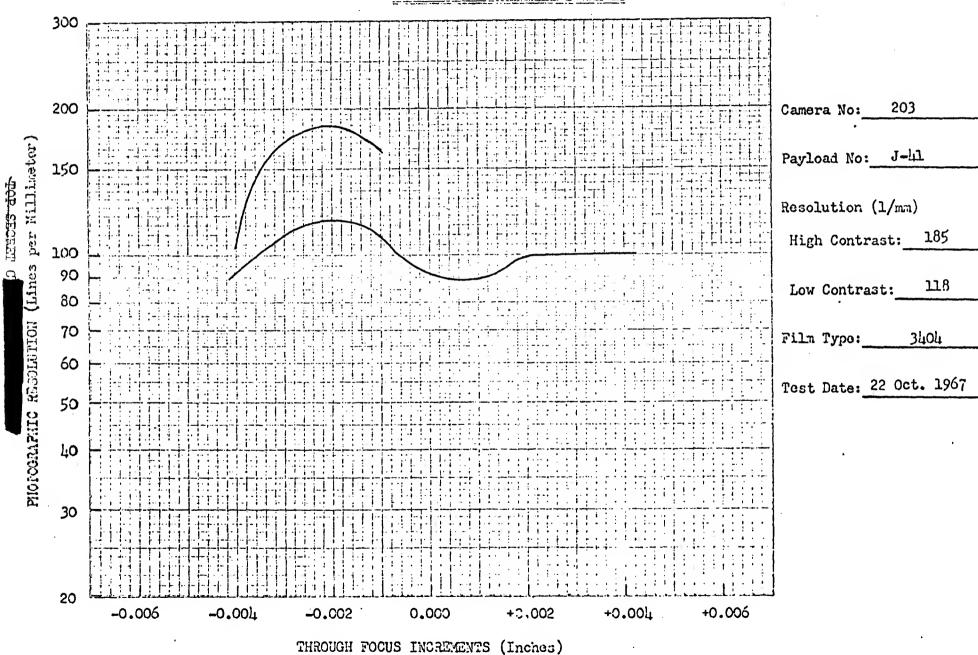
FIGURE 2-1

+0.002

+0.004

+0.006

PRE-FLIGHT DYNAMIC RESOLUTION



C. LIGHT LEAK TEST

The J-41 system was tested for light leaks on 12 August 1966, revealing major leaks at three of the four H.O. boot installations and at the Agena interface cover. Photomultiplier sensing techniques were used to verify the validity of repairs made.

D. FLIGHT LOADING AND CERTIFICATION

Loading of flight film was accomplished on 24 October 1967, and final pre-flight acceptance tests performed 25 October 1967. All functions were nominal, with no indications of light leaks or other sources of performance degradation.

SECTION 3

FLIGHT OPERATIONS

A. SUMMARY

Ascent through Agena ignition was nominal. The Agena engine "coughed" at approximately 128 seconds after Agena ignition and combustion chamber pressure was reduced during the last period of engine burn. The engine burned approximately 5 seconds longer than nominal. A hard engine shut-down was confirmed.

The achieved orbit parameters were low, but were within the three (3) sigma dispersions.

Both panoramic cameras operated satisfactorily throughout the flight.

Both Stellar/Index cameras operated satisfactorily throughout the flight.

The instrumentation system, clock system, and the yaw function generator performed normally for the duration of the flight.

An intermittent anomaly in the Lifeboat system developed in the -2 mission, with the possible initiation of an unplanned recovery sequence. As a result, the mission was intentionally terminated as early as possible.

Several commanding problems were encountered during this flight while commanding in the repetitive mode.

B. PANORAMIC CAMERA PERFORMANCE

Both panoramic cameras operated normally throughout the flight. Camera system dynamic operation, 99/101 clutch operation, start-up, shut-down, and film transport functions were normal on all monitored passes.

The cut and wrap operation and transfer to the -2 system occurred as programmed utilizing the KTK-ZORRO 38 command (early A to B switchover) on Rev 88.

The panoramic film was exhausted on Rev 140 frame No. 25 and frame No. 60 on the Master and Slave cameras respectively.

Panoramic Film Consumption

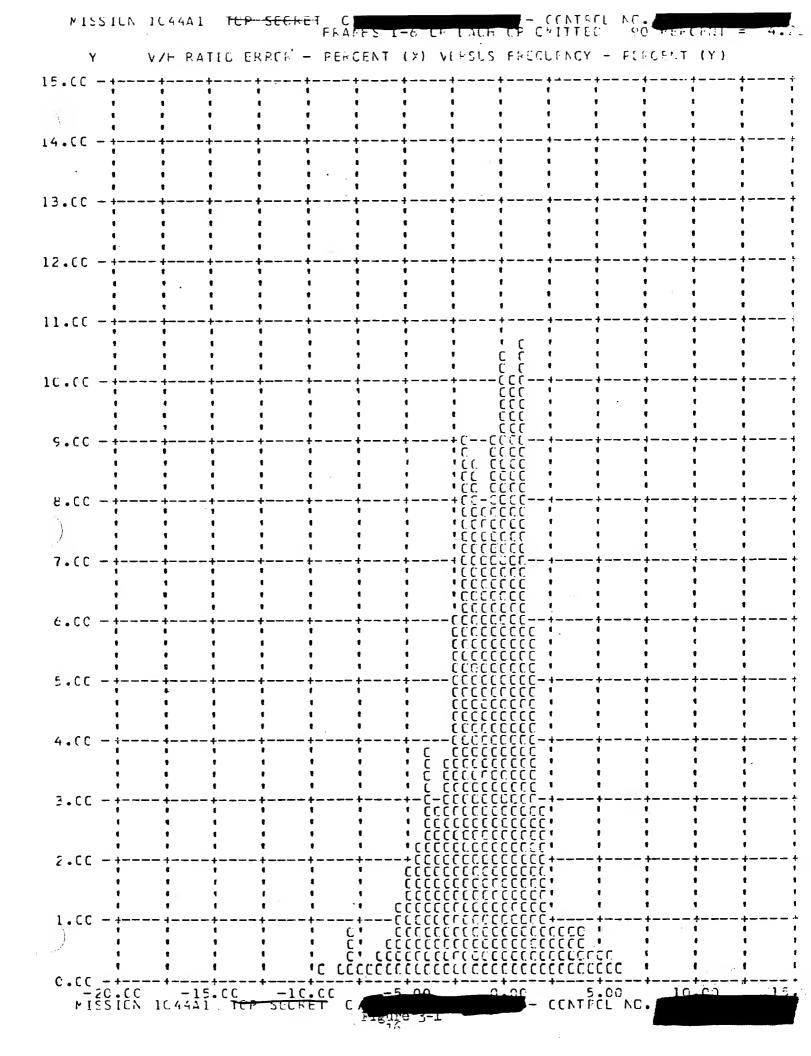
	Actual Frames	
	Master	Slave
Pre-Launch	137	137
-1 Mission	2898	2880
-2 Mission	3011	3 030
Total	6046	6047

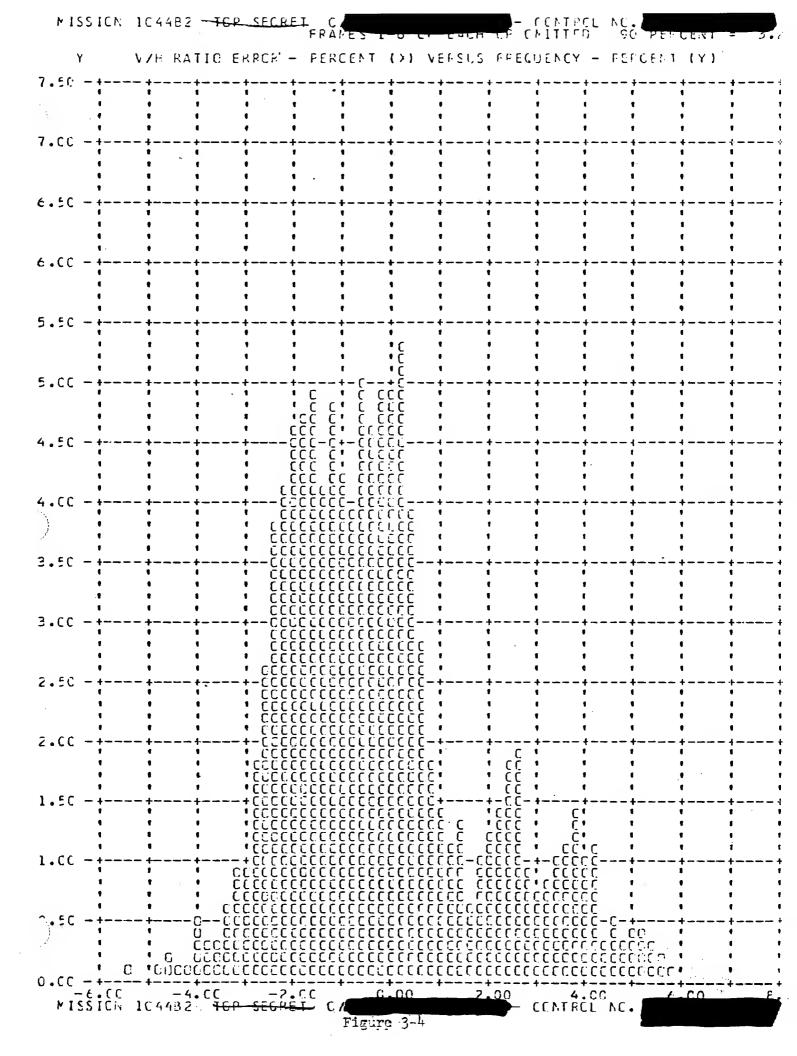
FMC Match

The V/H ramp to orbit match was acceptable throughout the flight. The following settings of RTC 6, 8, and 10 were utilized to obtain the optimum FMC match during the flight.

	RTC	Comm	ands	REMARKS
	<u>6</u>	<u>8</u>	10	
RTC Positions	7	4	6	Launch thru Rev 3
	7	2	9	Rev 4 thru Rev 12
	6	3	9	Rev 13 thru Rev 16
	7	3	9	Rev 17 thru Rev 44
	8	2	. 8	Rev 45 thru Rev 65
	7	3	9	Rev 66 thru Rev 75
	8	2	9	Rev 76 thru Rev 91
	7	3	9	Rev 92 thru Rev 114
	7	3	10	Rev 115 thru the end of the mission

However, the design of the 1000-series ramp programmer limits this optimum FMC match to a nominal band of latitude defining areas of primary interest. The extensive operations over a wide range of latitude experienced in this mission (Ref. Figs. 5-5 to 5-10) increases the statistical deviation, as is evident in Figures 3-1 through 3-4.





C. STELLAR/INDEX CAMERA PERFORMANCE

Both the -1 and -2 Stellar/Index cameras operated satisfactorily on all monitored engineering passes. Telemetry data indicated the programmer, metering functions, and shutter monitors performed satisfactorily.

D. INSTRUMENTATION AND COMMAND SYSTEM PERFORMANCE

The instrumentation system performed normally throughout the total mission.

The command system performance was satisfactory for both missions.

However, numerous command anomalies were encountered during the mission when real time commanding (RTC) was performed in the repetitive mode.

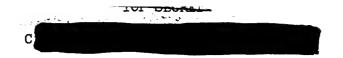
Analysis indicated that the RTC commands issued at the showed erratic command duration times. It was recommended that

the command generation equipment be verified for proper operation.

One RTC 9 was missed on Rev 56 while transmitting in the repetitive mode. The A/P stepper also failed to advance on two correctional commands and a third command was required to place the A/P stepper in the proper position. Analysis indicates that the stepper failed to respond to the issued command. A specific cause of this anomaly could not be determined from the available data. However, this command box was checked prior to shipment for proper command response time to command durations of 65 milliseconds and the system functioned normally.

E. CLOCK SYSTEM PERFORMANCE

The clock system operation was normal for the entire mission. Satisfactory time correlation between the flight clock and the was obtained. The ratio of clock time to system time was 1:00000026563.



F. PRESSURE MAKE-UP SYSTEM PERFORMANCE

The pressure make-up system performance was normal for the duration of the mission. Average gas consumption was approximately $8.4 \Delta PSI/min$ for the 240 minutes of total operate time. The system had a reserve of 620 PSI at the end of the flight.

G. THERMAL ENVIRONMENT

The thermal control pattern on this payload system was modified prior to launch to produce a thermal environment of $75 - 10^{\circ}$ F.

Temperature data from the acquisitions are included in Tables 3-1 and 3-2. The average instrument temperatures ranged from a high of 85°F. and 86°F. to low of 68°F. and 68°F. on the Master and Slave instruments respectively.

H. YAW PROGRAMMER

The vehicle Yaw Programming functioned properly throughout the mission. However, because of pre-flight programming error which placed the function start pulse approximately 800 seconds late, the Yaw attitude achieved was approximately 55 Degrees out of phase with the desired profile. A more complete description of this function and its effect on mission performance is presented in Sections 4, 7 and 8.

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I. RECOVERY SYSTEM

An early switchover from the A to the B Recovery systems was performed on Pass 88, with all functions appearing normal. The 1044-1 recovery capsule was successfully recovered by air-catch on Rev 97 at 1608 PST on 9 November 1967. Capsule impact was approximately 50 N.M. south of the predicted impact. All available data has been analyzed and all functions appeared to have occurred normally. All re-entry events appeared normal and close to the predictions except for deceleration chute deployment which occurred 0.12 seconds late.

	<u> Latitude</u>	Longitude				
Predicted	25° 56.4° N	165° 51.08° W				
Actual	25° 06° N	165° 42' W				

The intermittent failure of a relay in the "Lifeboat" system electronics during the 1044-2 mission resulted in several cases of inadvertent lifeboat timer starts as well as one case of power being applied to the primary recovery system. Because of the possibility of an uncontrolled recovery, the 1044-2 mission was terminated early. The 1044-2 recovery capsule was successfully recovered by air-catch on Rev 144 at 1509 PST on 11 November 1967. All re-entry events appeared normal and close to the predictions except for parachute cover off which occurred 1.97 seconds early. Capsule impact was close to nominal.

	<u> Latitude</u>	Iongitude				
Predicted	· 21° 0.56' N	154° 28.1° W				
Actual	21° 5.0' N	154° 33.0° W				

J. RADIATION DOSAGE

Each recovery system flown on a Corona mission contains a sealed packet of Eastman Type 3401 and Royal X Pan emulsions to determine the total radiation received at the take-up cassette. Both film types have been irradiated by IMSC at various levels and the base plus fog densities recorded after controlled processing.

Following recovery the film dosimeter packets are removed at A/P and processed with a pre-flight sample of the same film type and sensitometric control film. The resulting base plus fog density measurement of the dosimeter strips is used to ascertain the total radiation level. The table below presents the base plus fog readings for the dosimeter strips and the radiation level equivalents.

	Missi	on 1044-1	Missi	on 1044-2
	B + F		B + F	
Emulsion	Density	Radiation	Density	Radiation
Type 3401	0.22	0.9 R	0.25	1.3 R
Royal X Pan	0.27	0.5 R	0.30	0.6 R

These levels are below that which will degrade the photography.

SECTION 4

PHOTOGRAPHIC PERFORMANCE

A minimum of payload system photographic anomalies occurred during Missions 1044-1 and 1044-2, thus providing one of the most trouble-free flights to date. The image sharpness attained was considered equal to any previous Corona J-1 photography, permitting most imagery to be viewed at 60 x magnification. The overall image quality was judged to be generally good where not degraded by atmospheric attenuation; however, there was a predominance of cloud cover over the highest priority targets.

A. PANORAMIC INSTRUMENTS

The Master Camera produced 2898 frames (8049 feet) of photography during Mission 1044-1, and 3011 frames (7951 feet) during Mission 1044-2. The Slave camera produced 2880 frames (8009 feet) during Mission 1044-1, and 3030 frames (7963 feet) during Mission 1044-2. The quality of the photography produced by the two cameras was very similar, and was rated comparable to Mission 1035. The MIP Frames were rated 85.

The array of fixed resolution targets at Holloman AFB, New Mexico, were recorded during Mission 1044-2. The average system resolution of these targets was judged to be approximately eight feet for both instruments.

Both instruments exhibited characteristic anomalies, most objectionable of which was an appreciable build-up of emulsion particles. This condition was apparently accentuated by the very long operate times commanied during Mission 1044-2 so as to facilitate an early recovery. However, there appeared to be no significant reduction in information content because of this condition.

All auxiliary data recording functions operated normally throughout the flight, with the exception of missing binary data blocks on six occasions randomly over the missions. (Four occasions were on the forward camera, two on the aft). In each instance all of the other auxiliary data was present. This behavior was observed in pre-flight altitude testing, but was not considered detrimental so corrective action was waived.

The quality of the photography was adequate to readily identify intermittent bands of smearing near the takeup end of format caused by film flutter as the scan head enters the photographic format area. This anomaly is characteristic of instrument operation, and should be reduced considerably with the CR concepts.

It must be noted that this system was the first of the 1000-series to have the revised focus settings for a more precise compensation of the vacuum focal shift characteristics of the lenses used. Although there are many factors influencing the photographic quality achieved, it is reasonable to assume that the desirable performance of Mission 1044 verifies the validity of the new peak focus positions.

B. STELLAR/INDEX CAMERAS

The Stellar/Index film recovered consisted of 449 frames of photography from each film path of S/I D99/122/120 (Mission 1044-1), and 464 frames from each path of S/I D104/132/131 (Mission 1044-2). The cameras operated normally throughout the respective mission. There were 15 to 30 or more stellar images detectable on most frames despite a level of flare which affected approximately 50 percent of each frame. Most of the stellar images were good, and were point-type images. There was an appearance of Corona static marking occurring intermittently throughout the Mission 1044-2 stellar record.

The index cameras produced good quality imagery through each of the respective missions. The reseaus were sharp and well defined in both instruments. Several instances of dendritic static were recorded on the preflight, postflight and the last eight frames of the Mission 1044-2 index film.

C. OBSERVED DATA

Detailed evaluation of the engineering materials available at A/P indicated that the smearing effects from the V/h and yaw steering errors (see Section 8) did indeed create a detectable limitation to system performance in many instances in the mission. As predicted in the smear analysis, frames obtained with a large yaw steering error show a distinct disparity in quality between the forward and aft photography directly related to the difference in their exposure times.

When the ground smear contributions drop below some apparent threshold value (estimated to be approximately five feet for this system) on both instruments, the resulting forward and aft photography becomes very comparable and very good in quality. The Holloman AFB targets photographed during Pass 126 indicated approximately eight feet ground resolution for both instruments with a calculated theoretical smear of about $\frac{1}{2}$ feet (which corresponds to a theoretical ground resolution limitation of $\frac{1}{2}$ feet). In comparison, Pass 63 photography had noticeable disparity between forward and aft performance corresponding to relatively high smear values for the forward looking imagery (approximately $\frac{1}{2}$ feet theoretical smear induced ground resolution limitation).

The mission processing summary indicated a major disparity in original negative development in several instances throughout the mission. Evaluation of engineering pass 125 indicated that the aft-looking record, which was processed at the primary development level, had a significant loss of detail and image quality when compared with the corresponding forward-looking photography which was processed at the full level. There was excellent cloud highlight definition in the aft photography, but the important ground and culture imagery was suppressed to the extent of a distinct loss in information content.

D. PERFORMANCE MEASUREMENTS

A summary of MTF/AIM resolution values measured by SPPF is tabulated below. The microdensitometer slit used was 1 micron by 80 microns.

Mission	Camera	Cycles/mm	Avg	Ground Resolution
1044-1	Fwd	78	70	151
1044-2	Fwd	61	70	15 '
1044-1	Aft	71	70	13½¹
1044-2	Aft*	84	78	±3,5.

*Samples from portion processed by dual gamma method

The details of the measurement and computing techniciques, targets measured and target locations are fully reported in the evaluation report published by AFSPPF and are not included in this report. These values were determined by using the "Interim MTF/AIM Program" technique.

It should be noted that the value shown for 1044-2 Fwd camera includes one reading of only 32 cycles/mm. The reading may be accurate, but does not represent the nominal level of system performance. In comparison, visual resolution targets recorded ten passes after this reading location indicated an effective ground resolution of approximately eight feet, which corresponds to an MTF reading on the order of 130 cycles/mm.

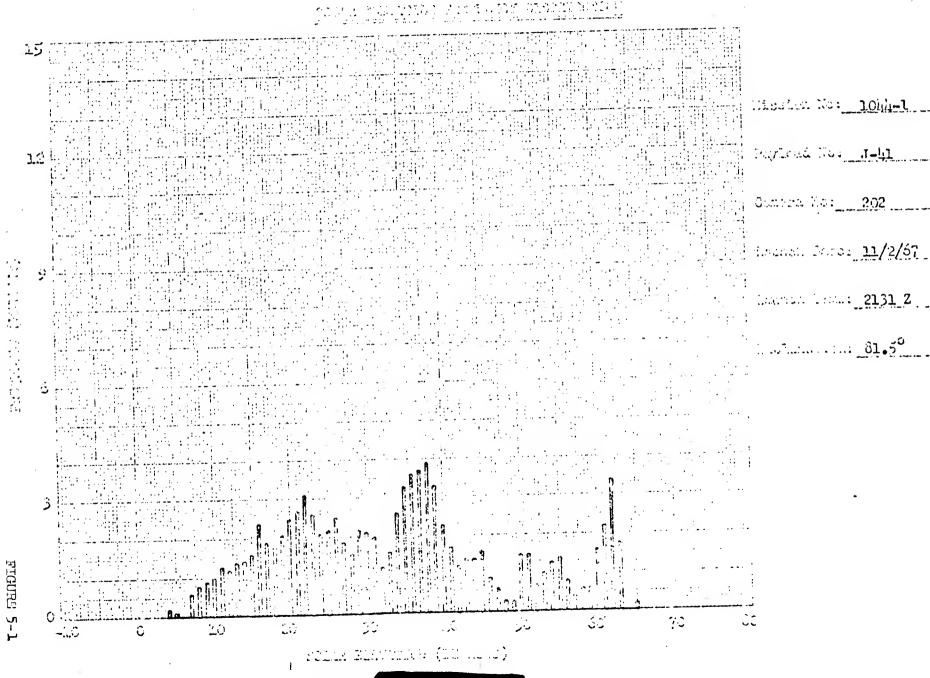
SECTION 5

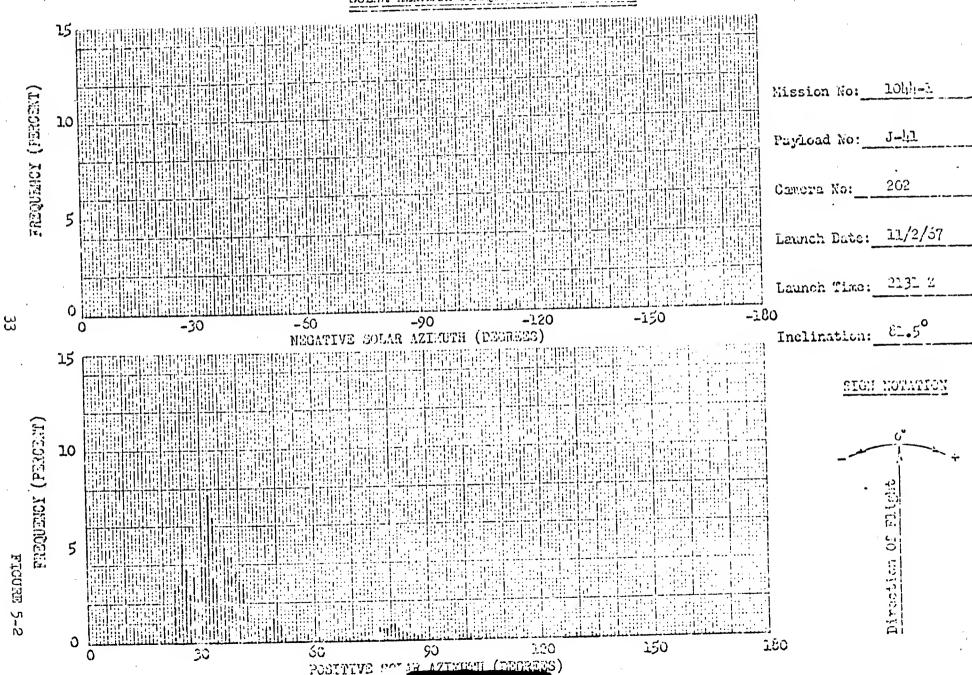
PANORAMIC CAMERA EXPOSURE

The Master camera contained a 0.200 inch slit and a Wratten 23A filter. The Slave camera had a 0.150 inch slit and a Wratten 21 filter. These conditions placed the nominal exposure between the full and the intermediate processing curve.

The frequency distributions of the solar elevations and solar azimuths encountered during the photographic operations are shown in Figures 5-1 to 5-4.

The nominal exposure times of the Master and Slave cameras are shown as a function of latitude for passes D-25, D-70, and D-116 in Figures 5-5 to 5-10. Superimposed on these plots are relative distributions of camera operations for the portion of the mission represented by each plot. These distributions became very uniform with latitude as the mission progressed because of the extended operations programmed in order to reduce mission duration.





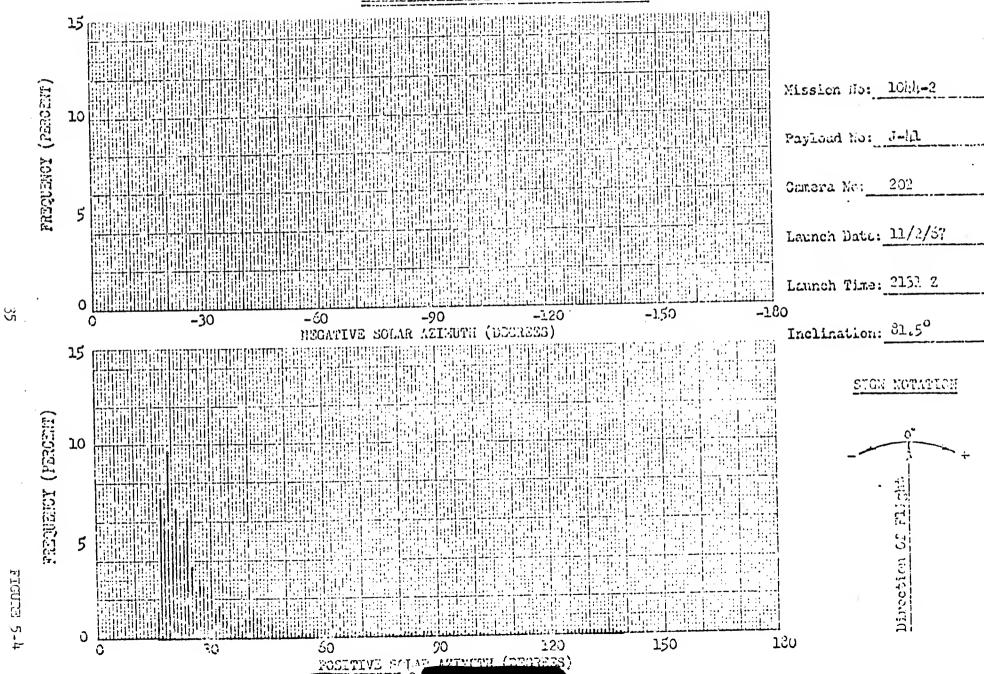
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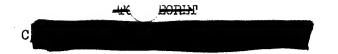
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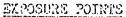
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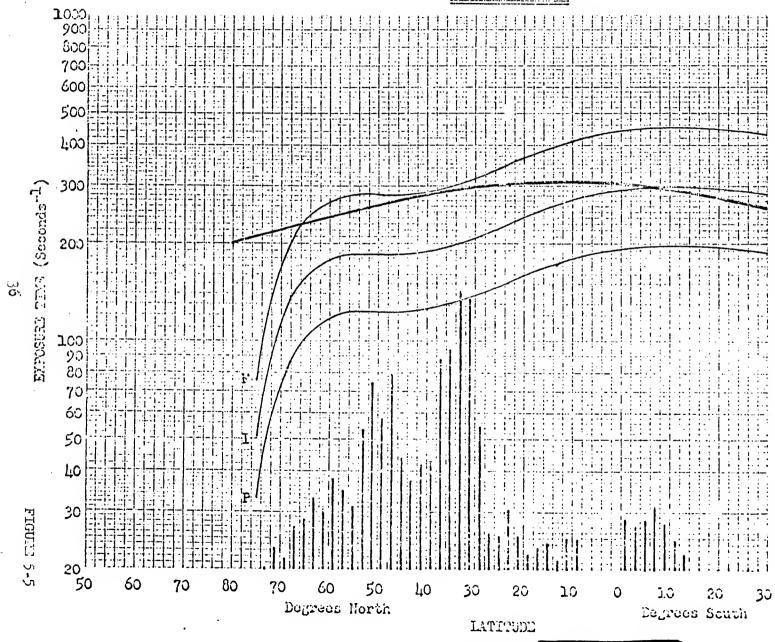


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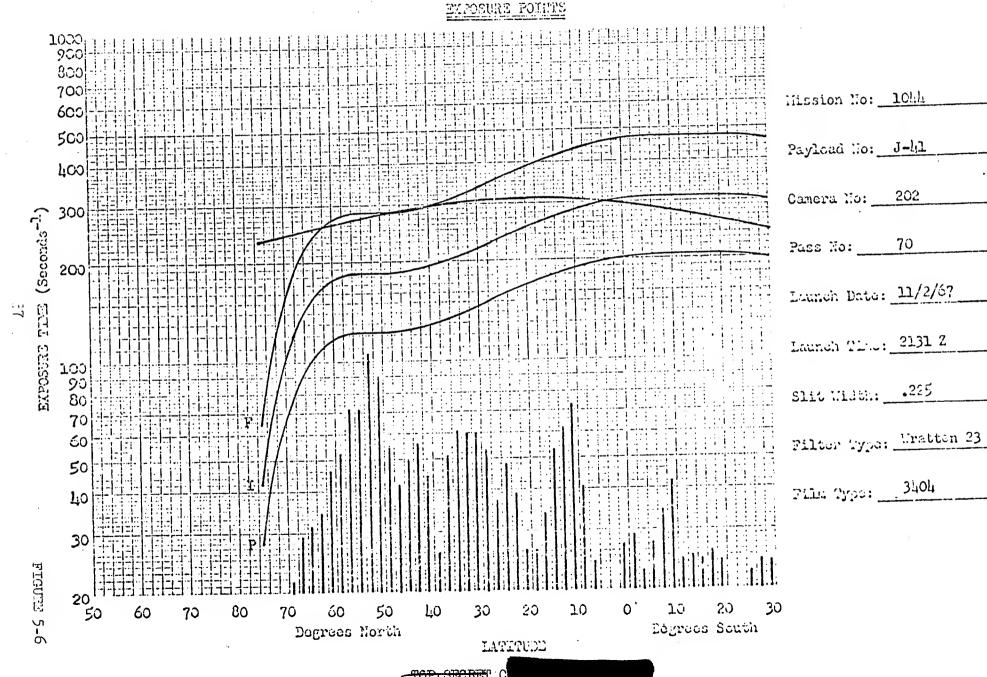




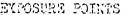


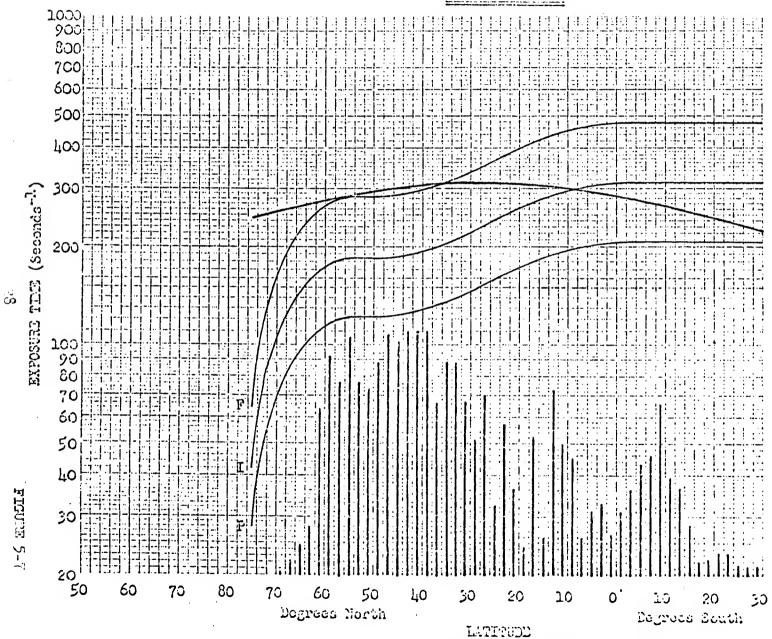
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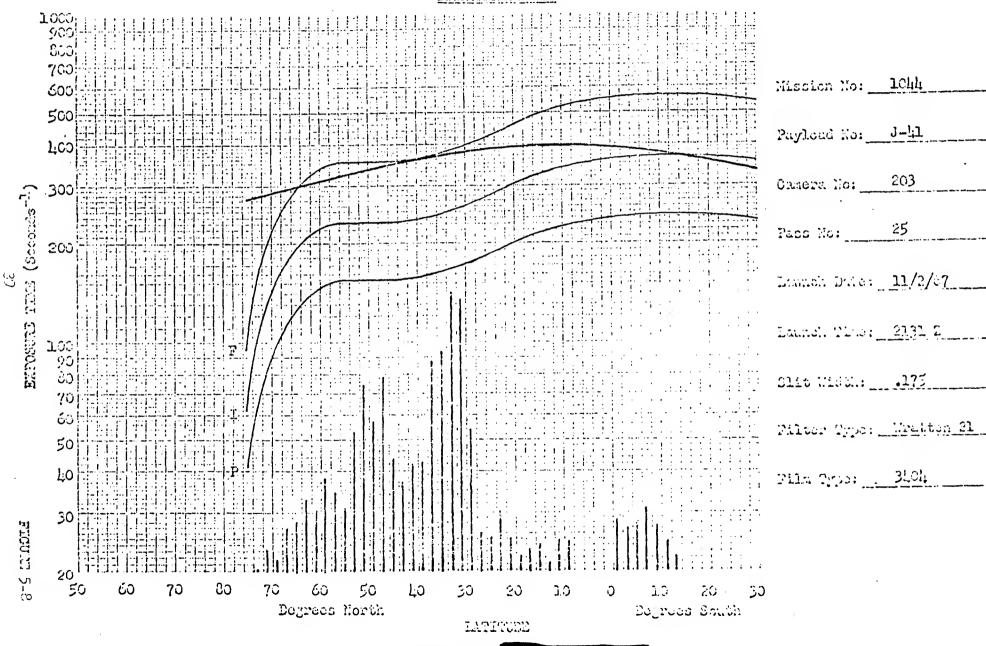






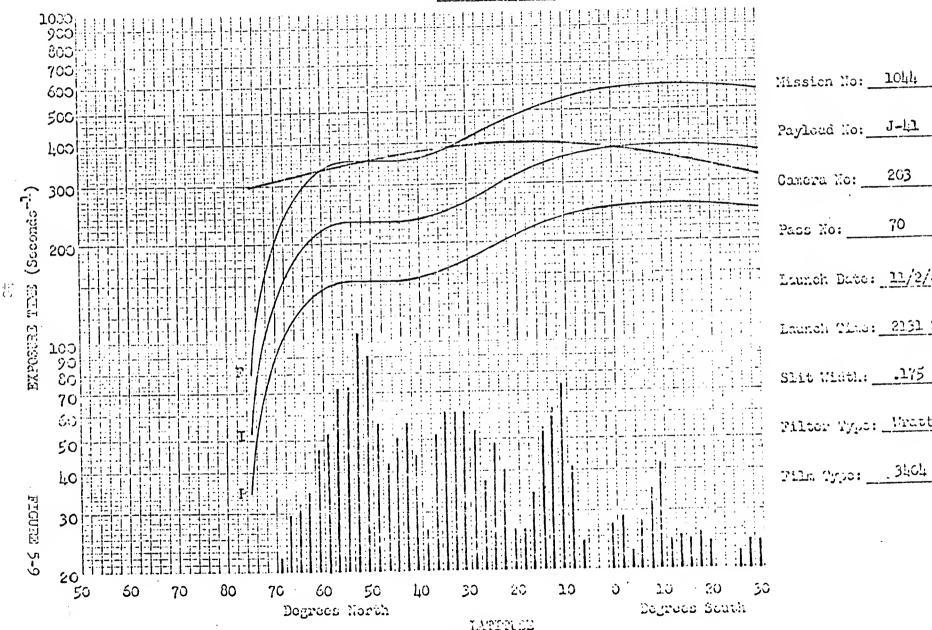
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Payload No:	J-1:1.
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Camera No:	202
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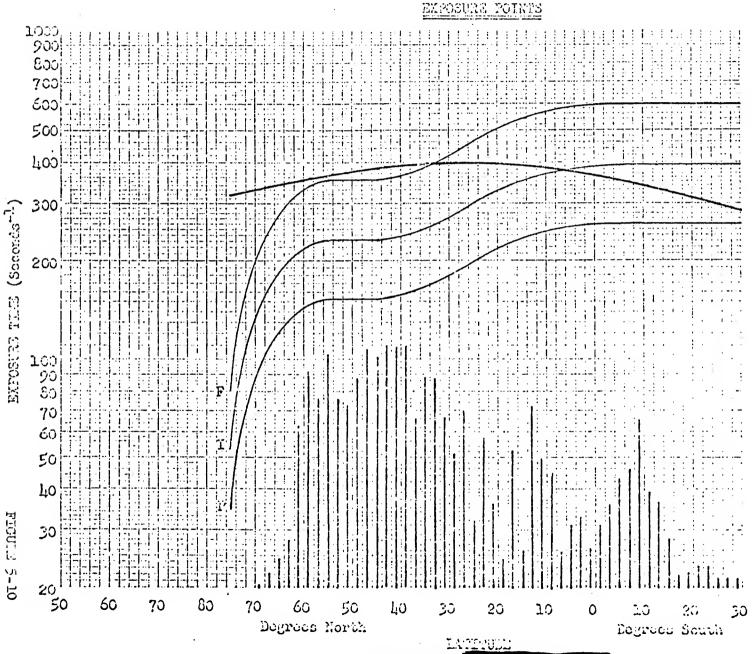






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Mission No: 10hh

Payload No: J-hl

Camera No: 203

Pass No: 116

Lunch Date: 11/2/67

Launch Time: 2131 2

Slit Misth: .175

Filter Type: Western 21

Pila Cyps: 31.04

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SECTION 6
DIFFUSE DENSITY LEASUREMENTS

The diffuse density measurements made by AFGPPF were computer sorted at A/P to permit analysis of the density ranges resulting from the three levels of conventional processing and from the dual gramma process experiment. The sorting technique utilizes the base plus fog density values for the conventionally processed materials where measurements up to 0.09 density are considered as having received Primary processing, 0.10 to 0.17 as Intermediate, and above 0.17 density as Full. The percentage of this material that was processed at each level, based on the computer sort, is tabulated below with the predicted and reported processing percentages.

Mission	Camera		Primary	Intermediate	<u>Full</u>	Transition
1044-1	Fwd	Predicted Reported Computed	0 0	13 6 8	87 88 92	- 6 -
10ħ ⁻ 1	Aft	Predicted Reported Computed	0 2 0	19 12 23	81 71 77	- 15 -
1044-5	Fwd	Predicted Reported Computed	4 0 0	16 4 7	80 92 93	<u>1</u> ,
1044-5	Aft	Predicted Reported Computed	8 5 . 0	24 17 28	68 63 72	- 15 -

Approximately 30 percent of the total mission original negative was subjected to a "dual-gamma" processing experiment. The results indicate a very effective reduction in the maximum cloud and snow densities with only minor influence in the normal range of terrain densities.

Graphical computer plots of the sampled density distributions are presented in Appendix A, Pages A-1 through A-48. Note the variation between the conventional processing plots and those for the dual gamma process. The differences in the cloud Dmax are very distinct. There is, however, a more subtle distinction that should be emphasized; namely, the incidence of lower terrain Dmin densities with the dual gamma process than with conventional processing. The reasons for these variations are obvious upon comparison of the corresponding sensitometric curves, Figures 6-2 through 6-13.

The sensitometric curves also illustrate the distinct deviations of the actual flight material processing from the standards and from the R-2 day samples. Obviously, there is need to maintain exposure control based on actual effective processed film speeds rather than on the standards. This will be especially true for the dual gamma process if future deviations continue to be as significant as was experienced in this case. As the dual gamma process becomes operational, it is anticipated that reliable processing controls will be attained. Likewise, it is anticipated that as additional progress in target density analysis is made a corresponding reliable exposure criteria will become a reality.

A surmary of the processing and exposure analysis for the conventionally processed material is shown in Table 6-1. The termin D-Min criteria, (range) for proper exposure and processing is 0.40 to 0.90 density units. The area measured for D-Min is believed subjectively and is not necessarily the absolute D-Min in the photography.

The terrain D-Min criteria has been found to be an inadequate indicator of optimum target exposure. Maximum intelligence is derived from specific target densities meeting this criteria; which, in general, results in overall terrain D-Min values repeatedly below the 0.40 density level. It is therefore apparent that the more desirable missions will, most likely, be reported as significantly underexposed by the present terrain D-Min criteria.

A density range chart, Figure 6-1, is included in this report. This type of chart for Missions 1004 to 1031 is included in the A/P final report for Mission 1031.

These charts are produced from the same density measurements previously mentioned in this section. The computer produced the mean, median and range figures for the various processing levels used. The chart includes the number of frames (samples) in which the density measurements were made. These measurements are made on approximately every tenth frame throughout the mission. It should be noted that the density figures shown for Missions 1044-1 and 1044-2 include both dual-gamma and conventionally processed materials, thus tending to artificially enlarge the apparent range of densities, especially for the cloud D-Max values.

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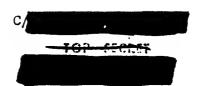
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PROCESS LEVEL	SAMPLE SIZE	UNDER EXPCSED	UNDER PRCCESSED	CCRRECT EXP&PRCC	OVER PRECESSED	OVER EXPOSED
PRIMARY INTERMEDIATE FULL ALL LEVELS	2 37 126 163	C PC C PC P PC 21 PC	0 PC 11 PC 0 PC 2 PC	0 PC 65 PC 65 PC	19 PC 19 PC 7 PC 10 PC	19 PC 5 PC 0 PC 1 PC
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PROCESS LEVEL	SAMPLE SIZE	UNDER FXPCSED	UNDER PRCCESSED	CORRECT CARRESTE	CIVEP PRCCESSED	OVER EXPOSED
PRIMARY INTERMEDIATE FULE ALL LEVELS	C 12 168 160	0 PC 0 PC 38 PC 36 PC	0 PC 0 PC 0 PC 0 PC	0 PC 42 PC 58 PC 57 PC	7 PC 58 PC 4 PC 7 PC	7 PC 0 PC 0 PC 0 PC
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PROCESS LEVEL	SAMPLE SIZE	UNDER EXPLSED	UNDER PROCESSED	CCRRECT EXPERSEC	OVER PROCESSED	OVER EXPUSED
PRIMARY INTERMEDIATE FULE ALL LEVELS	0 46 116 162	0 PC 0 PC 31 PC 22 PC	9 PC 25 PC 9 PC 7 PC	0 PC 50 PC 66 PC 64 PC	24 PC 15 PC 3 PC 6 PC	24 PC 0 PC 0 PC 0 PC
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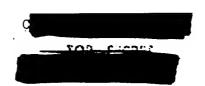
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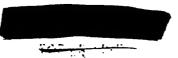
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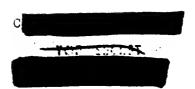


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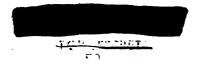


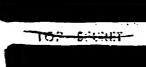


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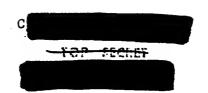


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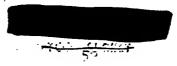


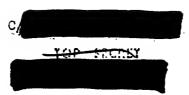


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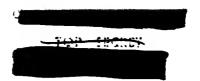
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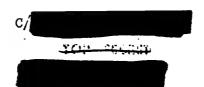
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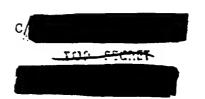


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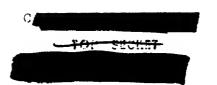
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SECTION 7

VEHICLE ATTITUDE

The vehicle attitude errors for both Mission 1044-1 and 1044-2 were derived from the reduction of the Stellar camera photography.

This attitude data is supplied to A/P by NPIC.

The attitude errors for each frame and the attitude control rates are calculated at the A/P computer facility. The computer also plots the frequency distribution of the rates and errors. Figures 7-2 through 7-7 show these distributions for Mission 1044-1 and Figures 7-8 through 7-13 for Mission 1044-2.

The summary table below lists the maximum attitude errors and rates that were experienced during 90 percent of the FWD camera photographic operations, excluding the first six frames of each operation, and the total range of the errors and rates.

	Miss	ion 1044-1	Mission 1044-2						
<u>Value</u>	90%	Range	90%	Range					
Pitch Error (°)	0.30	-0.35 to + 0.02	0.37	-0.62 to + 0.10					
Roll Error (°)	0.15	-0.28 to + 0.46	0.37	-0.57 to + 0.06					
Yaw Error (°)	3.42	-1.20 to + 3.80	3.31	-0.40 to + 3.60					
Pitch Fate (0/hr.)	14.53	-85 to +85	23.64	-65 to +75					
Roll Rate (º/hr.)	26.23	-58 to +76	30.62	-85 to +50					
Yau Rate (0/hr.)	51.28	-98 to +24	29.78	-80 to +10					

The yaw angle error represents the difference between the actual vehicle yaw attitude and the ideal yaw angle that would provide correct ground image motion. Because of a pre-flight programming error in the

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placement of the function start position, the yaw programmer was approximately 800 seconds out of phase with the desired performance. The large yaw angle error indicated reflects this condition. Figure 7-1 graphically depicts these relationships. The effects on image quality are discussed in Sections 4 and 8.

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SECTION 8 IMAGE SMEAR ANALYSIS

The frame correlation tape supplied to A/P by NPIC contains the binary time word of each frame of photography. A computer program has been assembled at A/P which calculates the exposure time of each frame and compares the camera cycle rate with the ephemeris to calculate the V/h mismatch (Section 3), which is then combined with the vehicle attitude error and rate values of each frame and the crab error caused by earth rotation at the latitude of each frame. The program outputs the net IMC error and the total along track and cross track limit of ground resolution that can be acquired by a camera regardless of focal length and system capabilities.

The computer rejects the first six frames of all operations as the large V/n error induced by camera start-up is not representative of the overall system operations. The frequency distribution of the IMC errors and resolution limits are computer plotted and are shown in Figures 8-1 through 8-12.

The surmary table 8-1 presents the maximum TMC errors and resolution limits that existed during 90% of the photographic operations and the total range of values during all operations that were computed.

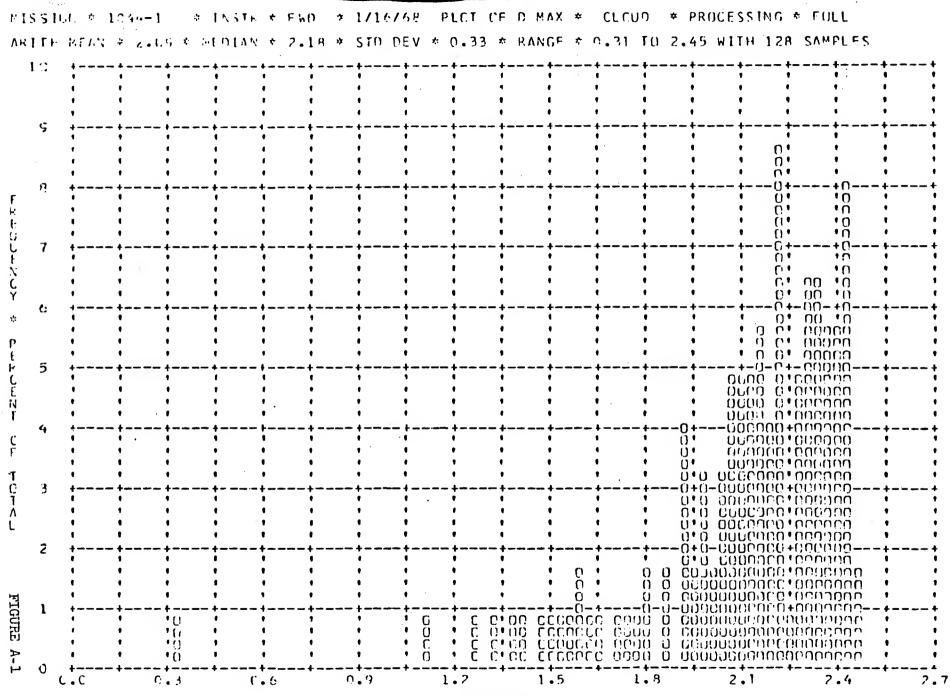
The relatively high values obtained in Mission 1044 reflect the combined effects of imperfect V/h and yaw steering matching as discussed in Sections 3 and 7. The apparent discrepancy in resolution limit values between the forward and aft-locking instruments is, in reality, a dramatic illustration of the relative influence of the difference in exposure time when coupled with smear contributing V/h and attitude errors.

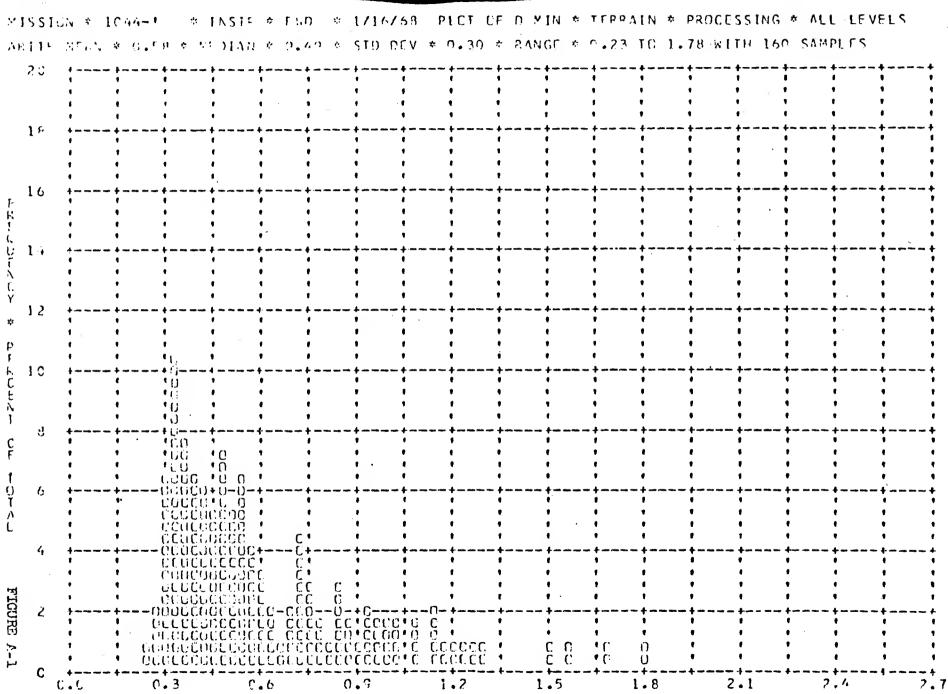
MISSION 1044 IMC RATIO AND RESOLUTION LIMITS

VALUE	units	CAMERA	MISSI <u>90%</u>	ION 1044-1 RANGE	MISSI <u>90%</u>	ON 1044-2 RANGE
IMC Ratio Error	K	FWD	4.55	-9.5 to +5.5	3.21	-5.4 to +6.0
		AFT	4.06	-10.0 to +6.5	3.26	-5.6 to +6.2
Along Track Resolution Limit	Feet	FWD	6.98	0.2 to 13.6	4.38	0.2 to 8.8
		AFT	4.36	0.2 to 9.8	3.25	0.2 to 6.6
Cross Track Resolution Limit	Feet	FWD	9.75	0.2 to 11.0	8.39	0.2 to 10.4
		AFT	6.19	0.2 to 7.6	5.30	0.2 to 6.0

TABLE 8-1

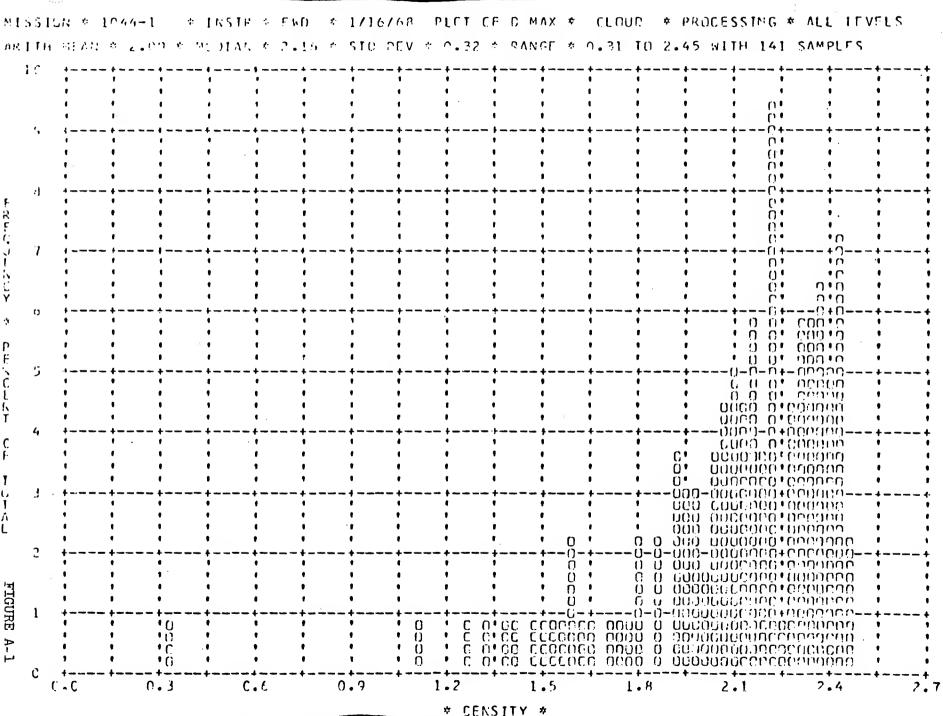
-7





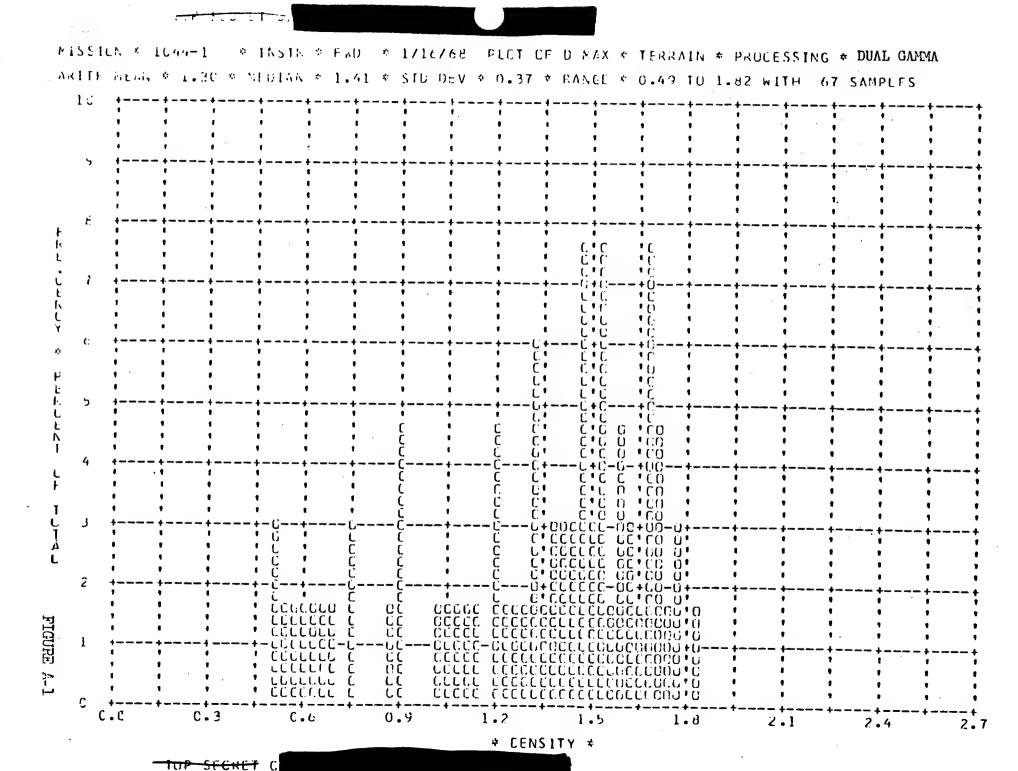
\$155H N * 1044-1 → INSTA + FWD + 1/16/68 PLCT OF D MAX + TERRAIN + PROCESSING + ALL LEVELS ARITH SEASE # 1.5% # MEDIAN # 1.59 # STD DEV # 0.39 # PANCE # 0.67 TO 2.36 WITH 160 SAMPLES 10 FRUER • 0 • 0 OC $0 \cdot 0$ • 00 • 0.6 C(0)(0)CO • 0 * 0 ree a cendar andra 3 0.00-0-0.00000+-0.001+0.0000תכס כ הסטטטטי תטטים ລີ ເບັນນິນຄາລິດີດີດີລີຂຸດ ຜົນນິ 00000 00000001000010 UÜ -0 *00000 *0000000 *000 00- **+** CC- C CC- CC CCOOOO + OOOOOOOOOOOO-O-O-OOO 'CG GGO GCCGGGC'GCGGGG GOO น อดก *CC 666 CCC660C*066000 000 0.000 0' FIGUE + n - - nn - nnagouo - CG cautuo Co an - an an an an an an an a • ຓ ຓຓຓ຺຺ຉຬຓຩຩ຺ຩ຺຺຺຺ຉຓຎຩຩຓຩຓຨ຺຺ຓຓຓຉຉຉຉຓຉຓຉຉຉຉຉ຺຺຺ຎຨຓຉ຺຺຺ຉຉຉຉ • ñ ang mimbba dababana•angabana•angaba 20•ang 3 5500 a CC.3 C.6 2.1 2.7

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Firming or

SECTION 9

SYSTEM RELIABILITY

Reliability calculations for the psyload are based on a sample beginning with M-7. Hence both the major part of the Mural program and the "J" program are covered in the calculation. For certain auxiliaries, i.e., the stellar-index camera and the horizon cameras, the sample size is changed to recognize incorporation of modified equipment or new designs where reliability was one of the principal reasons for the modification. However, for primary mission function, the sample size is consistent with reliability reporting for the vehicle.

The reliability estimates of this section deal exclusively with the payload. Failures to achieve orbit or vehicle induced failures are thereby excluded. Recoveries before a complete mission has been completed are considered as full missions providing that early termination was caused by reasons not connected with payload operation. Film quality is not considered in the reliability estimate calculation. Hence, only electrical and machanical functioning are considered.

The reliability estimate is also divided into primary and secondary functions. The primary functions are operation of the panoramic cameras, main camera door operation, operation of the payload clock, and recovery operations. The secondary mission functions are horizon camera operation excluding catastrophic open shutter failure mode, auxiliary data recording, and stellar-index camera operation. A summary of estimated reliability is shown in Table 9-1.

Fanoramic Camera Reliability

Sample Size - 195 opportunities to operate.

Two failures - S/I Programmer on System J-19

Film Transport on System J-42

Assume - 3000 cycles per camera per mission.

Estimated Reliability = 98.6 at 50% confidence level

Main Camera Door Reliability

Sample Size - 62 vehicles x 3 doors = 124 opportunities to operate Estimated Reliability = 99.5 at 50% confidence level.

Payload Command and Control

Sample Size - 11,424 hours operation in sample Two failures

Estimated Reliability = 96.1% at 50% confidence level

Payload Clock Reliability

Semple Size - 11,424 hours operation in sample No failures

Estimated Reliability - 99.0% at 50% confidence level

Estimated Reliability of Psyload Functioning on orbit = 96.5% at 50% confidence level

Recovery System Reliability

89 opportunities to recover

1 failure - improper separation due to water seal - cutter failure Estimated Reliability - 98.25 at 50% confidence level Stellar-Index Camera Reliability

Sample begins with J5 (Does not include DISIC units in 1100 series systems)

Sample size = 28,480 cycles

Four failures

Estimated Reliability = 93.3% at 50% confidence level.

Horizon Camera Reliability

Sample begins with J5 - 115,000

Estimated Reliability of Single Camera - 99.1% at 50% confidence level

Estimated Reliability of Four Horizon Gameras at a Parallel Redundant System = 99.9% at 50% confidence level.

ESTIMATED RELIABILITY SUMMARY

(AT 50% CONFIDENCE LEVEL)

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			98.0		99.0		96.3		98.4		94.8	90.4	36.7	
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1-6 21

ESTIMATED RELIABILITY SUMMARY

(AT 50% CONFIDENCE LEVEL)

			PRIMARY FU	INCTIONS			. SECONDARY	FUNCTIONS
MISSION	PANORAMIC CAMEHA	PANORAMIC CAMERA DOCRS SAMPLE	COMMAND R CONTROL	CLOCK	ON - ORBIT FUNCTIONS	RECOVERY SYSTEM	STELLAR - INDEX CAMERAS	HORIZON CAMERAS
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	104	76	5376	5376		41	9830	46,500
1021	98.5	0 99.1	97.0	98.8	96.9	96.0	89.1	97.
1022	1112	80	5784	5784	96.9	45	11,550	51,000
	99.5	99.2	97.3	98.5		96.3	90.7	98.
	114	82	6000	6000		47	12,190	54,000
1023	90.8	99.2	95.8	0 93.9	96.2	96.5	2 91.1	39.
	118	184	6240	6240		19	13,040	57,000
· 1024	98.6	0 99.2	96.0	98.9	96.3	96.6	91.6	98.
1025	122	86	6480	6480	96.4	51	13,890	60,000
1023	98.6	\	96.1	99.0	30.4	96.7	92.1	98
1026	126	88	6720	6720	-96.5	53	14,740	63,000
	98.7	99.2	96.3	99.0		96.8	92.6	98
1027	128	90	6744	6744	36.5	55	15,165	64,500
	98.7	99.2	36.3	99.0		97.0	90.0	99
1028	132	92	6960	6960	96 .7	57	16,015	67,500
	98.7	99.2	96.4	99.0		97.1	<u></u>	ł
	136	94	7200	7200	96.8	59		70,500
1029	98.6	99.3	1 7		30.0	97.1		
1030	140	96 O	74402	7440	96.9	61	17,430	73,500 0
	98.9	-				97.2	89 3	98.
1031	143		7704	7704	96.9	63	18,280	76,530
1031	98.6	0 99 3				97 3	89 7	

ESTIMATED RELIGIBLITY SUNNAF

(AT 50% CONFIDENCE LEVEL)

				JACTIONS			SECONDARY	EURCTIONS
FICEION NUMBER	PARSHAMO GAMERA	_	COMMAND & CONTROL SYSTEM	1163.1	ON - ORBIT FUNCTIONS	REGOVERY SYSTEM	STELLAN - INDEX	nC8(2CA CAMEAAS
non-o-r	Sample FAILURES	SAMPLE FACTORES	SAMPLE FAILURES	FAILURES	RELIABILITY	JAMPLE FAILURES	SAMPLE FAILURES	SAMPLE FAILUNES
	FCCAB ATY	HCLIAD LITY	·· · · · · · · · · · · · · · · · · · ·	REGIABILITY	·	ne Lining	ACCUMPANTA	31. 4.
:033	\$0.9	100 C	Ł	7908	97.1	as 	- 4	79,500
	151	.02	d20a	02Cc -		67	7.4 90.5 19,960	62,500
	98.9	993		. 0 59.2	97.2	_ ! 	7.5 50 S	3
.635	195	· ·	•	· · · · ·	37 .~	71		03,500
			- <u></u> 97.1_	9520			7.6 91.3	
1030	. 93)	· · 0	2 97.0	99.2	97.3	41	¶ 4	85,500 ఎ
1037	163	С	9043	5048	97.4	/3	22,530	91,500
	59.0		97.2	99.3		1	7.7 51.6	0
1038	990	0	2 .	9336	97.5	75 .	23,360	94,500
		1112		9600		_ 97 77	24,230	
:039	99.0	99.4	97.4	99.3	97.5	97	4 92.1	0
1040	175	0		9840 C	97.5	79	25,040	100,500
	99.0		97.4	99.3			92.4	
1041 .	99.1	0 99.4	2	0	97.6	1	e 4	103,500
245	103	118	10,536 1	10,536	,	83	26,760	06,500
1042	99.1		• .	0 99.4	97.7	93	. " 4	0
1043	187		2	10,89 5 0	97.2	ป5 I		000,000
···	98.6	99.4	97.7:	99,4		38		,

COP-CHORDE C

ISTMATED MELLANDEY SUMMERY

(AT 50% CONFIDENCE LEVEL)

			ÉDBLARY FI	UNGTIONS			SECCHDARY	FUNCTIONS
n daron Noncen	611.1.1.1.1.1.1.1.1.1.1.1.1.1.1.1.1.1.1	Altanama Gerigia La Sauria	COMPANO A CONTINU	.) P.18.233 6.334	ON = GADIT FUNCTIONS	RECOVERY SYSTEM	STELLAG - HOEX CANZEAS	ication Come as
1,014 2 2 59		1 0 3 0 175 10 1 1 1 1 1 1 1 1 1 1 1 1 1 1 1 1 1 1	Factoria	FARTER	ALLIADILITY	FAILURES :	FAILURES	2-19-11
1,01		138	11,000	11,500		167	12,003	112,000
	900				- # # 9c.5	85.1	3 77.2	
1044	99.0	د الاستسسن	2	11,463	98.5	100	1,49,490	ن مارون الم
	55.0	00.6	66.1	53.0		90.2	63.3	
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SECTION 10

SUMMARY DATA

The comparison of the operating parameters and the performance achieved by previous missions has been difficult due to the large volume of data that results from each mission. Some of the pertinent characteristics from prior missions have been summarized in Tables 10-1 through 10-3.

The summary data was started with Mission 1004 as the J-05 comera system was the first to incorporate the major modifications of the titanium drum and scan arm, four roller scan head and Corona J capabilities. Only those missions that culminated in the recovery of some photography have been listed, therefore Missions 1003, 1005 and 1032 are deleted.

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MISSION SUMMARY

	<u> </u>		T	1	OHEIT		GE I.			TEH CAN			VE CAM		STELLAR-II.	
MISSION NUMBER	PAYLCAD A 11. A	VEHICLE NUMBER	LAUNCH DATE	LAU'-CH TIME	Inclination	ALTITUDE (MM)	LOCATION	RECOVERY PASS	CAMERA NUMBER	SL 11	FILTER	CAMERA NUMBER	SL11	FILTER TYPE	CAMERA NU	ADER
100-	J-05	1174	2/15/64	2138 2	74 9	99.9	29.0	49 :12	124	0.250	W - 21	125	0.250	W-21	023/29/29	D42/42/37
1006	J- 09	1176	6/4/64	2259 2	79 9	84.0	63 2	65 128	148	0 200	W-21	149	0.200	W-21	045/47/45	049/53/42
1307	J-07	1009	6/19/64	2318 2	e5.0	99.2	41.5	65 128	114	0 250	W · 25	145	0.200	W-21	043/43/43	D54/5G/51
ಚಾರ	J-10	1177	7/10/64	2314 2	85 O	99 4	40.8	49 112	150	0 200	W-21	151	0.200	W-21	048/45/40	033/28/33
1000	J-12	1605	8/5/64	2316 2	80 1	99.6	39.5	19 128	154	0.200	W-21	155	0.200	W-21	056/54/56	038/30/34
1010	J·II	1176	9/14/64	2254 2	84 9	97.4	42.5	65 144	152	0 175	W-21	153	0.175	W - 21	041/41/41	
1011	₩-3X	1170	10/5/64	2150 2	79.9	99.3	20.9	65	150	0.175	W · 21	161	0.175	W - 21	030/30/30	D41/4E/44
1012	J-13	1179	10/17/64	2202 2	75.0	96.2	32.4	49 81	156	0.200	W-21	157	0.200	W - 21	051/51/47	057/57/57
1013	J-15	1173	11/2/64	2130 2	80.0	100.0	25.0	65 01	158	0.225	W · 21	159	0 225	W-21	052/49/55	046/52/53
:0.4	J-16	1160	11/.9/64	2036 2	70.0	103.2	65.6	3: 145	162	0.250		139	0.175	W-21	N53/59/49	047/48/54
1015	J-17	1607	12/19/64	2110 2	74.9	96.7	21.5		138	0.250	W-25	141	0.175	W-21	D61/61/61	030/44/46
1016	J-16	1608	17:5765	2101 7	74.9	99.4	30.2	175	132	0.250	W-25	133	0.175	W-21	055/55/50	058/58/58
1017	J-14	1811	2/25/65	2144 2	75.0	97.2	25.9	159	140	0.250	W-25	165	0.175	W-21	021/21/21	059/50/59
1013	J-19	1612	3/25/65	2111 2	96.0	100.2	40.3	66	122	0.250	W-25	123	0.175	W-21	020/20/20	060/91/1
1019	J-04	1614	4/29/05	2144 2	85.0	99.1	27.1	80 99	118	0.250	W-25	119	0.175	W-21	019/35/35	022/22/22
1620	J-20	1613	6/9/65	2158 Z	75.1	97.1	40.6	97	136	·	W-25				007/85/80	019/18/19
1021	J-21	1615	5/18/65				l	113	 	0.250		137	0.175	W-21	063/69/69	002/05/65
	·			1803 2	75.0	109.2	24.3	65	166	0.175	W-21	167	0.250	W-25		025/27/25
1022	J-22	1617	7/19/65	2201 2	85.0	99.7	30.3	144	168	0.250	W-25	169	0.175	W-2i		024/24/24
1023	J-23	1618	6/17/65	2100 5	70.0	97.8	29.0	144	170	0 225	W-25	171	0 150	W-21		D66/75/72
IC24	J-24	1619	9/22/65	2131 2	80.0	95.9	18.4	161	172	0 225	W-25	173	0.150	W-21	· · · · · · · · · · · · · · · · · · ·	DG4/82/66
1025	JX-28	1618	10/5/65	1746 2	75.0	112.9	44.3	161	142	0.175	W-21	127	0.175	W-21		D70/83/81
1026	J-25	1620	10/28/65	2117 2	75.0	93.0	17.0	e1 160	174	0.225	₩-25	175	0.150	W-21		072/09/85
1027	JX-27	1621	12/9/65	2110 2	80.0	97.4	17.3	17 33	184	0.250	W-25	163	0.175	W-21		068/74/83
1028	J-26	1610	12/24/65	2106 2	80.0	97.6	28.4	81 144	176	0.250	₩-25	177	0.175	W-21	077/81/97	074/76/95
																RECIJON

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Mission sunmary

					i čnt	.9. 19			L				7		STELLAR-11 CAMERA NU	
		Vindué N.V., R		12352A 7356	INCL (1.47.05)	AL/17606 (187)	(*N)	RECOVERY PASS	CAME HAT NUMBER		3471	CAMERA NUMBER	(-)	FILTER	· · · · · · · · · · · · · · · · · · ·	
	J-27		2/2/66	2132 2	75.:	99.5	22 5	61 163	178	0.275	W-25	179	0.175	W - 21	0/9/04/61	0767707
ا ند		1655	3/9/66	5502.5	75 0	97 5	18.7	رين ال	102	0.275	W- 25	193	0 175	W-21	094/100/107	561260
.521	J-30	.227	4/7/66	2202.2	75 1	104.5	23 3	113	164	0 225	W-23A	185	0.150	W-21	083/101/89	Lasmod
	v - 20	(625	5/3/66	1925 2	!				180	0 150	W-21	:81	0 150	W-21	561/97/:01	- - và0//3
	3.33	.010	5/24/66	6213 2	, ,,,,	102.0	60.7	1 62 176	194	0 200	W-21	195	0.200	17-21	591/105/109	0347102
7:14	. 31	1	6/2./36	2131 2	, a0.1	105 4	18 2	61 161	192	0 200	W-23A	137	0 150	W-21	CI.5/(09//G	257.407
agety	2 · 2 ·		:	2:4/	5 5	99 9	29.1	الماسية الماسية	106	0.225	W-23A	:69	0 175	W-21	042115 VIS	13000
.035			0/5/60	2040 Z	.650	162 4	22.9	11:5 2.2	193	6.200	W-23A	191	0 150	W-11	Salvitonii	6: 47t
: -: :7	11.24	1217	11/6/66	15:: 7 d	156 0	9. 6	14.5	1.6	150	0.225	W- 23A	:59	č 175	W-21	0.007.207.28	 : c
	6 A 6	19629		. I i i i i i i i i i i i i i i i i i i		56 9	29.2	ы ы	192	0 225	W-23A	193	0.175	W-21	Duszadzinia	់ឯលាកា
	<u></u> .	.635	2/22/6/	2.62 3	600	97 0	30 2	01-177	206	- - - 0 225	₩-23A	207	0.175	W-21	2003/141/132	ב על טוג ב על טוג
	J- 35	: :030	3/30/07	1854 2	BS.i	90.7	26.3	161 145	106	0.175	M-51	:97	0.223	W-23A	079755705	
:04!	J+40	634	5/9/57	2152 2	ù5.1	150.1	33.5	93, 215	308	0.225	W-23A	209	0.:75	w.gi	[3:05:13:00s.	0.027.2
	3.37	1623	6/16/67	2130 2	0.08	96 S	29.1	57 240	204	J 200	W-23A	205	ن.I 5 0		357/180/117	
:043	J12	1337	8/7/57	2164 2	au.o	102.1	16.3	113	200	6.200	W-23A	201	0.150	W-21	0:07/131/135	CHEVIS
1:0:	CK+1	1641	9/15/67	1341 2	80.0	84.6	5.7		362		W-21	303	*	W-23A	DISIC N	
•								208		.	V/- 23.3		.	W - 2:	099/1227/20	• •
1644	J-41	: :39	. 11/2/67	2131 2	81.5	93.9	18.4	144	202	0.225	W-537	203	0.175	M-51		5.047.3
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-102 GEOFFIE C

PERFORMANCE SUMMARY

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M SUIDN A MA ER	CAMENA	Similar Contra	M P VALUE	NICHAL RES		AFS FIFE AVENTAGE	\$1177 \$117		S. 11 (M)	<u>.:/[</u> 4[[HioH		TITUDE ERF	PAW	_90 % AT	TITUDE RATE	\$ [%%] YAW	90% V/H ERROR (%)	90% RESOLUTIO ALONG TRACK	CHOSS TRACK
10:)4-1	FWD	124	85	70 66		37 60		109 36		115	127	0 4 5	0 42	1 08	30 0	25 0	210	5 I	7.7	6.1
1004-2	FWD AFT_	125	85	76 73	350	88	43	113	320	8 2 8 3	90 95	0 74	0 50	0 91	44 0	30 0	29 0	4 9	8 8	6.5
1006-1	FV.D	140	90	73 74		65 71		88 90		84 87	97 92	0.41	0 42	1 14	26 8	28 5	27 8	15 4	13 8	6 7
1004-2	AFT_	149	90	35 85	350	6-l 72	43	8 I 90	320	គ4 87	90 34	0 49	0 40	1 08	31	27 9	30 O	11.6	10 1	7.0
1337-1	FWD AFT	144/	85	80 86		60 63		87		82	91	0 58	0 46	1 43	37 6	23.9	29 9	3 6	3 1	9.4
1207-2	FWD Af T	145	85	79 81	350	72	43	63 81 92	320	57 68 74	74 81	0 64	0 47		43 0	25 8		4 6 3 2 4 2	2 1 2 4 1 8	7.6
1008-1	FWD AFT	150/	85	80		80		95		31	89	0 5 3	0.39	0 94	43 8	23 9	29 6	2 9	4.9	5 9
1008-2	FWO ATT	151	85	76 82 79	350	75 84 91	43	89 96 83	320	85 83 85	95 92 91	0 63	0.36	071	42 9	24 0	32 5	2 8	4 2	5.4
1003-1	FWD AFT	154	8 5	92		ao				75	38	0 65	0.65	071	29 2	22.7	27 6	3 3	5 3	5 8
1009-2	F #C	155	85	89 94 87	350	85 85 87	-		80	75 76	63 84	0 48	0.65	0 59	33.6	23 9	27 2	2 6		
1010-1	FWO	152	8 5	90		90		83		72_ 87	⁷⁹ 96	0 93							4 9	5 9
1010-2	AFT FWO	153		88 92	350	86 81	80	80 82	ao	92 82	103		0 30	0 87	39.1	23 6	30 8	4 5	2.3	4.4
1011-1	FVO	160	85	-90		62		85		87	96	0.59	0 70	1.21	45 4	23 6	30.7	4.6	7 5	3.8
	AFT	161	90	84	350	76 77	80	96 96	ao	78 83	87 93	0.77	0.39	0 97	43.1	28.9	31.1	2.3	5.3	5 6
1012-1	F WO	156	8,5	92 91		_	80	91 87	80	84 89	98 100	0 65	0.51		47.1	53.2		1.5	4.8	
1012-2	FWO AFT	157	85	89				89 96		84 85	9 I 9 0	0.97	0.77	0 51	45.2	30.7	20.4	5.9	3.3	5.9
1015-1	FWO AFT	159	8 5	89 77			60	94 97	80	85 81	99 103	0 64 0 64	0.32 0.32	1.34 1.34	36 9 36 9	29 0 29 0	32.3 32.3	3 7 4 5	7.8 9.6	8 3 8 2
1014-1	FWD AFT	162	80	87 83				78		74	86	0.62	0.41	1.46	35 0	36 :	33.5	2.2	6.2	3 A
1014-2	FWO	139	80	83 86		_	80	80 75 84	80	95 70 80	107 77 88	0.62 1.06 1.06	0.41 0.55 0.59	1.44	34 8 38 4	36.0 36.4	38.3	3.3 1.4	2.8 6.4	6.3
1015-1	FWD	138	85	87				76		90		0.65	0.38	0.53	38.1 47.0	36.0 29.4	38.2	3.2 5.0	5.5	
1015-2	FWO	/141	85	87 83		-	80	. 73 . 72	80	97 89	-	0.64 0.50	0.29	0.53 0.64	46.9 39 I	29.2 27.1	39.2 36.2	6.3 3.2	3.4 6 B	7.8 5.5
1016-1	FWG	Y		82				72		90		0.5C	0 61	0.64	3 <u>9_1</u>	27.0	36.3	3.3	4.6	7.5 5.3
1016-2	AFT FWD	132	85	85 83 90			80	56 61	80	81 94		0 72 0 72	0.83 0.83	2.01 2.01	48.9 48.4	30.2° 30.1	40.4 40.4	2.0 2.8	5.5 3.4	10.5 7.4
	AFT	133	85	91				55 56		92 91		0.83	0.93	2.19	42 2 42 2	27.2 27.3	39.5 39.0	1.5	4 9	8.0
1017-1	FV/O AFT	140/	85	72 75			80	57 70	80	78 94	86 107	0.49 0.49	0.76 0.76	2.50 2 49	35.5 35.3	32.2 32.0	38.4 38.5	3.3	9, 8	11.6
1017-2	FWO AFT	165	85	85 85			80	65 69		80 86	94 101	0. 6 9 0 59	0.45 0.45		36.5 36.3	34.0 33 8	<u></u>	1.8	8.3 6.2 5.3	8.1
10:8-1	FWJ	122	65	79 77				70 74		82 96	92 109	0.91 0.90	0.48 0.47	·	47.4 46.2	36.7 36.2		3.4	5.6	
1018-2	FWO	123	85	84 88		_	80	75 71	80	77 91	89	0.64	0.63		34.7	30.7		3.2 3.1	3.7 5.6	
	*	·				L					103	0.03	0.63		34.8	30.7		2.8	4.1	AEC/10H

PERFORMANCE SUMMARY

TOP SECRET C

	Care sa		4	l Version				Adentic						74 (* <u>)</u>		<u>activities</u>		95.E AN4	3.4	1.00 T 10-571
15.3-1	F	110	us.	1 5	, —	_	60	13			151	0 44	0 55 0 37	0 97 0 98	31.6	34.7 34.9	33 0 33 1	3 ; 3 3 ; 3	9.3 5.0	75.42K
15.5+2	1 2 4 5 5 5 5 5 5 5 5 5 5 5 5 5 5 5 5 5 5	35/	-	20 23 ———		_	80	6.2 6.2	60	71. 94 —	165	0 - 6 6 - 1 C - 1	0.35 0.35 0.17 0.17	0.75 0.73 1.56 1.05	27.4 27.4 27.6 42.6	31.3 31.3 23.4 23.8	26.7 26.7 42.5 42.5	5 . 4 5 . 3 3 . 5 3 . 4	5 9 4 2 6 4 4 5	6 4 5.5 7.6 2.9
1021-1	F.A.2 	/167	65 65	6.0 5.0 6.5 7.4			ပေ	77 50 79 62	80	66 99 60 —	69 105 112	0.55	0.37 0.33 6.35	0 81	34 9 34 8 44 7	32.6 52.0 53.6	26.2 26.3	2 . 7 5 . 4 3 . 1	8.6 5.6 6.2	8.3 5 5
1955 - 1	1 Ar T 1 Ar T	165 /	US	90 92	 	_	60	' 23 ' 23 ' 66 ! 92	80	76 101 76 93	94 11. 94	0 47 0 40 0 40	0 5 1 0 5 1 0 5 1 0 .5 1	0 65 0 55 0 55 0.50	28.5 27.9 29.4 29.4	27.4 06.6 27.3 27.3	25.8 23.8 51.0 31.1	3.5 3.0 2.3 1.8	9 8 6 0 8 0 4 9	S 6 6 1 8 4 5 9
1023-2	(22.3 (2.3 (2.4 (2.4 (2.4)	170 / / 17 /	65 - 65	· —.	:			## #7 -7: -53_	uo	57 63 76 68	110 101 57 75	0.49 0.45 0.43	0.33 0.33 0.25 0.37	0 55 6u 0 55 0 53	33.0 33.9 29.7 29.6	23.7 20.7 21.0 21.3	23.5 23.6 23.6 23.6	3.4 3.5 2.4 2.5	4.0 2.7 3.5 2.7	6.4 4.3 4.3 4.2
1024-1	140 4/1 740 147	1:72 /	63 61	: ! 		_	ĿΟ	77 55 66 66	ชอ	90 94 160	102 165 101	0.42 0.42 0.34 0.26	6 25 0.25 0.31 0.31	0.62 0.62 0.93 0.93	32 2 32 2 30.4 30 6	24.9 24.5 23.6	40.5 30.4 36.4 36.4	2.0 2.1 5.5 5.1	5.9 3.5 4.7 3.3	6 b 4.5 5 4 3 6
1525-2	1 % 2 #6 7 # 2 0 # 2 1	192	85 65			_	ده	67 97 85 91	6 ·3	65 191 191	97 116 107 103	0 50 0 51 0 53 0 53	0.41 0.42 0.44 0.44	0.35 0.85 0.62 0.62	28 1 26 6 26.0 28.1	26.7 29.7 26.1 26.0	25 9 25 7 29 0 29 0	2 0 3 2 1 7	3 9 2 3 4.7 6 7	6.7 0.11 0.0
1026-1	7W5 AFT FW5 A7T	174	აწ 85	_	_	—	90	7 G 68 95 93	80	- 30 98 92 90	52 113 104 103	0.65 0.65 0.65 0.59	0.24 0.24 0.55 0.65	G 70 0 70 0.87 0.85	37.9 37.5 41.1 43.3	33.2 33.2 46.5 50.0	28.5 28.5 30.8 27.7	0 : 0 : 6 : 0 :7	13 5 9.1 9.5 3.3	0.2 4 6 7
1527+1	FWD Al'T	163	Ü5		_		90	69 73	60	82_ 80		0.51 0.51	0.37	0.74	47.2 47.3	25.5 25.2	26.4 26.2	4.7 3.6	10.5	7 2 5 2
1020-1	AFT FWD AFT	176	ช5 85	 — 	_		80	61 92 88 77	пo	89 93 87 84		0.52 0.75 0.76 0.76	0.37 0.37 0.52 0.12	0.50	36.6 36.6 42.7 42.5	28.0 28.0 25.7 25.6	30.5	3,9 3,1 3,2 2,9	4.0 4.0 2.2 3.3	8.0 5.u
1525 - 2	FAD AFT FWD AFT	178	65 65		80	10 - (10) 50 51 63 51	60	95 62 94	60	77 73 77 81		0 07 C 48 0 04 0.65	0.34 0.33 0.48 0.48	0 77 0 77 0 44 0 44	29.1 28.5 38.6 37.5	31_3 30_8 32_5 32_1	34.4 34.6 25.7 25.7	0 0 4 6 2 3 3 6	7.6 3.5 7.5 2.9	7.4 4.3 7.5 4.9
1530 - 1	FWO FFT FVO AFT	102	95 85		86	95 74 77 91	80	70 79 81 74	80	66 77 71 71		0.67 0.67 0.70 0.70	0.25 0.25 0.27 0.26	0 35 0 59 0.67 0.67	29 6 29 6 26 4 28 2	22 7 22 0 21.7 21.9	30 1 35.9 36.3 36.3	3.9 5.4 4.9 5.6	u.9 5 1 4:.2 0.6	8.0 0.0 9.0 5.5
1031 - 1	FWD AFT FWD AFT	184	85 85		80	65 57 91	03	76 71 94 —	80	60 66 74		0.50 0.54 0.57	0.47 0.41 0.20	0 95 0.31 0.75	16.2 18.1 19.6	17.3 18.7 19.3	26. u 22.6 15.7	6 I 0 Ú 5 4	13.8 12.0 10.3	0.4 5.0 4.9
1033 - 1	FWD AFT FWD AFT	194	85 35		0ò	77 67 75 93	86	94 93 90 92	60	67 72 50 73		0.11 5.15 6.21 0.20	0.33 0.27 0.24 0.24	0.80 0.39 1.09 1.00	11.3 8.2 22.3 22.3	34 9 55.6 49.3 50.7	27.3 19.5 17.5 17.4	3.5 4.9 2.6 2.9	5.2 0.1 5.6 7.3	0.2 5.0 0.9 6.7

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1 2 2 2 2 3	CA30.344	langen.	Maria de Maria de	•	3417 (44)				V.2.	अ:राज	6.32.2	Y.W.	ERBOK (%)	ALONG THACK	CROSS THACK	ERACA
44/4	7.85	.00	1,5	73	:	41 90	i. 20 0 20	5 i.i. 5 i.i.	0 09 0 99	19.3 19.3	20 4 20 4	24.9 24.9	15.0 15 2	17.5 13.5	5 6 4 .a 7 . i	
15/4+2	45.5	137	63	74 60	60	ა) მა	0 44 0 34	0.36 0.36	0, 33 (35	21 1	0 65 0 65	15 2	8 7 8 9	10.4 8 o	5 3	
1335-1	417	101	ل ئ	55	. I		0 10	0 54 ; 0 54 ;	1 30 2 43 3 92	(8.9 3.3 (1.4	25 4 25 4 30 1	33 9 32,2 27 5	4 0 4 1 5 2	4 8 3 7 4 0	2 4 3.5	3 2
1035-2	Hay Harris	ا دد کرا	<u> </u>	81			370	_3 51 	3 02	31.2	24.7	20.5	3 4	3 3	0.4	3 4 -
.036.62	4 W 3 1 1 1 1 1 1 1 1 1 1 1 1 1 1 1 1 1 1	103/	EJ LS	9%	50		0.76 0.94	5 95 6 76	0 (6) 0,40	31 . 53 0	25 5 17,7	29.4	3.3 5.3	3 6	5 i 6 5	
11.75.27.77			65	- 			0. M 6:5	0.76	0.45 : 50	3: 9	42.0	23 3 29 3 32.4	9 5	i 0 :	0	s ii
1.5.7-2	51.1 5.1	176	65	10	50		0 15 6 34 6 17	6 17 6 36 0 42	. 51 7 1 .14	75 7 16 3 53,5	3.19 52.5 30.6	20 2 53 4	6.6	5 4	7.5	6 3 7 0
1532 + 1		102	 ວຽ		·		0.72 0.77	0.75	2.95	41.6	357	39 9 34 4	3 G 3 4	4.1	3.7	3 5 3 7
10-35-2	1.42	1.15	ة ن	77	. uo		6 35 6 33	0 51	2 57 2 90	20 0 50 4	28.3	27 8 27 3	3 4 5 4	3 6	33	3.1
10.9-1	1	2::4	65	5.3 7.	t O		0 ::1 0 ::0	0s 0 .::	3 63 3 65	19 .0 37 .5 33 .1	23.0 30.2	39.2 28.5 25.0	5 I 5.2 4 C	0 2 4.6 5.5	7 2	5.2
10000-2	FWS AFT	207	65 	71 .			0 30 0 36 0 33	0 54 0 56	2,50 2,52 2,99	27.1	24.2	23.9	4.8	3.9	2.1	5 0
1340-2	#### 4# 1 ##9	196	85 ชช	5-4 60 61	80		0.20	0 50 0 40	3.00 2.90	22 I 27.5	23 2 30 0	28.5 32.5	2.1 1.G	1 /9 2 2	2 5 2 0	2 1
1341-1	- AFT	97	65	-\frac{75}{72}	<u> </u>		0.34	0.40	2 56 3.05	14.7	26.4 14 G	12.7	5.1	2.5	3 4	2.6
1941-2	FWO AFT	209	65	62 75 78	60		0.35 0.23 0.28	0.16 0.23 0.24	3.05 2.94 3.01	15 8 22 9 23.9	13 5 15 7 16 2	13.0 18.8 21.0	5.8 4.5 5.6	5.7 5.4 5.5	3 0 2 1 2 0	57
1342-1	FWD AFT	204	ù5	79			0.3:	0 22	2.66 2.83	22.1	36.3 33.0	27.0 25.9	3.1	3.3	1.5	3.1
1042-2	FWD AFT	205	85	70 74	80		0.31	0.38 0.37	2.39 2.31	16.1	46.1 33.6	31.4 25.6	2.1	2 5 2.3	2 2	2 3
1043 - 1	FWO AFT	200	85	67	60		0.28 0.31	6.23 0.23	3.11	23 9 25.4 29.2	22.0 20.5 31.6	41.5 34.9 47.9	4.2 3.3 4.3	5.4 2.8 5.3	~ 0 U	4_2 3_3 4,4
1043 - 2	FWS AFT	201	35	65 75			0.30	0.34	2.73	27.3	29.9	45.1	3.1	2 6	0.5	3_2
1101-1	2113 2117 1110					*					*				*	
1944+:	AFT	/		76			0.30	0.15	3.42	14.6	26 2	51.3	4 2	7.0	9 6	4.0
1544-2	FWS	262	85	7 I	80		0 3G 0 37 0 37	0.16 × 0.37 0.38	3.36 3.31 3.27	16.1 23.6 23.5	. 24.2 30 6 24.5	42.7 29.8 28.8	4.1 3.0 3.2	4 4 4 3 3 3	6 4 5.3	3 2 3.3
<u> </u>	AFT			84												
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3-01 RTPS-5

* DATA NICT COCCENTIVE AVAILABLE

EXPOSURE-PROCESSING SUMMARY

·		F 10	ΔR	571	11.	Tri -	11:57		F: 5 (HILD	T 66	veut	63.1																		
W-55'0N		ELEV		4.71	به ∙ر د		15551			เรราะว		CESS			PRAI	N D -	VIN			N D-V	ΛY		เดยว	D - M	ΛX	UNDER	UNDER	HOWINAL	OVER	OVER	CLOUD
NUVEEN	CAVERA	100	jinga !	TAN. Luai		jT	", []	ا¦-ړ٠	ii T	^) (- ;	[⁶].	r-, -	LUX.		NL V4	NEDIAN	LOW		ME AN	VEDIAN	FOM H7.		VL AN	VEDIAN	EXPOSED	PROCESSED (%)	EXP.8 PPC	PROCESSED (%)	EXPOSED	COVER
1004-1	FWD	-3	51		124	5		12		79 17		73	21	0 26	1 80	0 83	078	0 43	E 43	1 97	202	1 00	f	2 04	2 08	0	4	60	31	5	35
1004.2	451 500	-3	60	25	124	5 7		27		70 17 50 13			20			0 75 0 83		0.35	2.45	1 92	194		2 37		2 03		4	57 59	26 27	3	35
1004.7	AFT	-4	67	10	131	7				0 13		77			191		0.73		2 30		199		1	130	1 58	0	4	67	20	9 9	35 35
1000-1	7.2	3.0	55		140		22	ာ	- 1 -	51 49	_		1 1		1-31	9.71	0 66	0.90	2 31	1 58	1 52	_	240	1	2 24	0	5	72	21	;	60
1006-2	FWO	38	64	5.2	147		97	5		7 5 7 7 7		3.4		0 26	1 56	087	0.50	0 56	2 35	1 72	172 150		5 40	2 11	2 16	0 2	21	50 72	40		60 45
	AFT	32	64	31.	147	7	9.0		1	0 25	1	34		0 2 5		0 62	0.53	0 65	2:3	148	147			212	216	ō	īi	77	9	3	45
1007-1	201 =	12	49	50	103	0	5	95		20 73		1			1 22	0.52			2 20	1 4 1	140				2 2 1	20	8	67	5	0	60
1007-2	Fig	32	57	43	112			75		62 49 88 63				0.50	1.75	0 58	0.55	0 75		1 52	1 52 1 4 0			2 20	2 24	1 18	13	. 83 71	5 2	0	60 65
}	_ AS T	31	57_	20	111	•	100	ᅟ이	1	41 45	1 3	0.0	, ,	- 1	1 56		0 56	044	2 27	1 50	1 52	0.64	2 41	2 17	2 25	l!	1.6	74	9		65
1009-1	FA9 AFT	30	51	50	102		1001	6		32 64 27 69		33		0 32 0 32	1 48	0.65	0.63	0 78	2 24	1 55	1.54 1.58		2.35		2 24	2	2	·8G 84	8 13	1	45
1008-2	FWC	29	56	4.3	105	0	00	ŏ	3 3	31 66	0	27	73	214	181	0.76	0.72	0 57	2 10	154	155			2 20	2,25	2	;	73	23	0	45 65
1003-1	.ΑF7 Γ''/Ο	29	5G 49	.42	105	- ·	100	- 2		30 67	1	23	il	- 1	1 64				2 10		155		2.35		2.22		3	69	27	0	65
İ	AFT	12	49	42	132	0	100	0		06 73 60 60				0 32	1.40	0.65 0.70		0 85	2 2 2 9	1 53	52 55		2 51	2 30	2 36	5	5	77 73	14 20	Ů	50 50
10:00-2	FW3	23	59	35 35	138	2	28			21 76		10			1.55		064	0 73	2 37	1 53	1 53	1 06	2 45	2 25	2 30	4	4	74	17	ŏ	55
1010-1	- F%D	18	57	45	138	2	99	79	1	47 47 13 07	1 "	56	ł	0 26	1.47	0.69 0.52	0.64	0 44	2 42	1 G1 1 38	160		2 50		2.34	18	3	77 75	18		55
ļ	AFT.	19	47	45	83	0	21	79	0	19 61	0	16	84	0 27	1 25	0 57	0 52	0.71	2 42	1.45	141		2 4 G		2 26	9	. 4	81	4 6	0	48 48
1010-5	F i O	15	52 52	36	7G			50		16 84 23 77		13 25		0 26	1.51	055		0 52	2 36		138		2 44	2 14	5 55 5 50	13	4 3	67 76	6	o	45
1011-1	FWO	2	55	33	EG	0	64	36	2 2	23 75	-	23	1	· ·	0.93		l	0 56	2 36		1.43		2 40		2 15			70-	8	0	45
1012-1	AFT FWD	. 2	55 45	-33.	-56 71	2		33		7 50	1	37		0 2 4	•	0.60		0 50			1.55		2 37	2 11	2 18	3	7	8 <u>i</u>	ē	ŏ]	40
10121	AFT	0	45	36	71	8		36		3G 37 33 G7		65		0 25	1.30		0.53	0 54	2 39	1.40	1.42		2 39		2 00 1 9 G	6 5	17 10	68 74	10	0	60
1012-2	FWD AFT	0	57 57	34	106			23	6 4	4 50 5 82		49			1.20	0.50	0.55	0 73	2 32		1.42	0 67	2 34	191	2 00	4	9	60	7	0	40
1013-1	FWO	- c	56	28	93	- 		36		2 59	ł	55	· i	0 20	1.27	0.56	0.62	1 1	2 33	1.55	1.58	~ ~	2 38	2 03	2.02	7	13	72	23	°	40
l	AFT	0	56	26	82	0	54	36	-5 -	7 9!	Į.o	33		0 28		0.66	0.48	0 64	2 28	i.59	1.63	1.10	2 36	1 1	2 03	5	5	74	16	0	47 47
1014-1	FWD AFT	0	59 59	15	71 69			79 69		18 5 I 13 87	0	63 36			0.99 1.25	0.40	0.36 0.48		2 36	1.40	1.42	-	2 38		2 05	27 19	33	39		0	40
1014-2	FWD	0	77	0	36	o l	21	79	0 2	8 74	0		39			0.36	0.31	0 23	2 32	1.30	1.36		2 43		2.00 1.80	31	12 40	54 27	5 2	0	40 40
1015-1	AFT FWD	0	76		34			71	1	5 95		68	32	- 1		0.44	0.40	, ,		1.34	1.45		2 44		1.84	19	29	50	2	_ 0	40
.0.3-1	AFT	5 4	68 69	19	68 67	0		92 70		2 96		2		0 25 0 0 29		0.54	0.47		2.28	1.44	1.46	0 4 5	2.41	1.86	1.90	28 14	0	65 77	7 8	0	45
1015-2	FWD	0	80 79	-2	71 71	0	10	90	0 1	0 90	0	11	89	0 22	1.10	0.50	0.46	0 34	2 07	1.29	1.30	0 28		1.69	1 78	28	4	65	3	8	15 40
1016-1	FWD	0 5	69	-2	76		- 1-	79 93		9 91	-	59	I	0.26 0.13		0.59	0.52	0 36	2 2 2	1 37	1.38		2 40	1 - 1	1.80		:	70	12		40
	AFT	4	69	12	76	0	27	73		6 74	0			0 2 2		0.5 ł 0.6 4	0.45 0.58	0 70	2 34	1.67		0.85		1.91	1.90 1.92	19	17	5 G 6 2	8	1	45 45
1016-2	FWO AF7	١	84	-4	76 76			92		1 69 7 72		48	52	018	1.56	0.48	0.44	0 29		1.45	1.44	0.34	2 50	1.76	1 82	22	18	56	3	ò	40
1017-1	FWD	-11	50	21	99	5	-3			3 24	-0	40 82		0 20		0.55	0.49	-	2 32	1.52		0.30 0.60		1.75	1.82	23	5 6	-65 77	e	!	10
1017-2	AFT	-!	57	19	96	0	17	83	24 5	8 18	4	90	6	0 20	1 62	Ú G4	0 50	0 60	2 29	1 75	1.75	81.1	2 36	1 83	1 90	i	13	74	13	2	25 25
1017-2	FWO AFT		70 79	7	139 135	8	위			2 33	7	77 83		0 22	1.54	0.58		0 37	2 30	1 70		0.36		1 93	1 94 1 92	3 2	14	74 74	9	Õ	30 30
10'8-1	FWD	G	77	13	134	0	0			3 28		83	-	0 19	1 46	-		1)	2 22	1 66	1.73	****	2 32	56	1.99	2-	-19	71	-10		35
1010-2	AFT	6	78	10	125	0		78		3 38		72		0 18		0 62	0.58		2 20	1 60	1.80	103	2 28	1 95	2 00	1	12	77	9	ž	35
1018-5	FIVO AFT	8	77	14	134	0	15	65		4 0		73		0 22		0.57		0 50		1.50			2 26	1.05	101		31	56	35	4	45
		•	اـــــــــــــــــــــــــــــــــــــ										طــــــــــــــــــــــــــــــــــــــ	التت			لــــــــا	. 						التسلم							

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มหราส	CANTHA		<u></u>			-,;	1/17	; - 	:	-,,	- - ا الم			a sitt	year.	velar:		eren e	មនេះគ្រ	rED an	To:	11.515	ME ARE	ED AN	EXPOSED (%)	1001.5000	(p)	(5.)	r.)	("::
10154	FAL			2				19 F.C 19 F.C			4 56					a.s: 0 60						2 26			4 1	7 13	64 70	17	7 3	45 i
1 1020-1		23	75 75	19		c'	154 8	ين أبو	43	50	1 56	411	اليجو	1.30	0.55	0 52	اوء ہوا	::0	57 .	154	: :01	2 331	210	2.16	1	18	7 A	4 5	C O	42 42
1620-2	1.1 ·	197	69	17 .	35	0	S4: 3	36¦ :5	1.0	!"" -	0174	188	0 2.5 ji	1.20	0 1/5	0,54			JEF		ĖΝ		2041 - FY A	7.13 TA	0	16	′.,	3	,	
i	2.7	1 4 - 1	G'	17	33 '	٠.	c:.	12/14	201	47	٠,١,,	47	2	1.50	0.64	0 58	i •					2 35	<i>Un</i> .	\	5	9	72	-11	3	35
l otter	A.C. (110	**** 1*	: 17		O	5.	1 15	:311	47.	0:57	1 43 }	6 17	1 70	0 65	0.5	U SH	4	1.45	132	0 65	2 30	1 507		5	5 13	75 66	12	0	35 20
1.0.2.2	. • AD	13.	-		-41 } -41 }		- 1	0 5 5			0 50	56:	0.33	: 3a	0 76	0.50 0.76	0.73	2 30	1.52	i.50	1.36	0.30	1 94	1.54	· ·	_ 0	71	_21	ļ. <u></u> 1	
1502-1	1.77	2	57 1	3.0	100	°i		54 B	300	ί. 51 τ	0 42					0.40	0 54			,		2 55		2.25 2.25	30 4	15	47 71	3 9	1	35
1000.45		1.0	74 !		35.2 ° 3.5 7 ±	0 1	ု ရုံ (၁၁)	ngi i Olin		-	0 43					0.35						2 45 2 45			35 10	2 B 2 5	35 61	1	C C	45
1023-1	FAD	l re i	1.2			5	5 ! :)5 ¦ 15	3.9	8	0,72	1,8	0.15	i au l	0 59	0.35		2.44	:	128	ប្រាវ	2.45	. 00	2.11	20	14	3.4 65	2 7	0	35 35
+023-2		25	1.1		:77	6	7 :	0 33 0	151	211	0 10	6.2	0 22	1.38	0 48	0.42	041	2 03	1,14	122	0.90	2 41	2 03	2.11	35	10	73	2	1 0	35 31
1024-1	7.74 CW3	20	-0 -	-13	179	0.¦		37 5 30 0			0 72						0.44 0.40			1.15	0.50	2.34	1.97	2 03.	27	49	23		0	35
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EXPOSITE PROCESSIVE SUMMARY

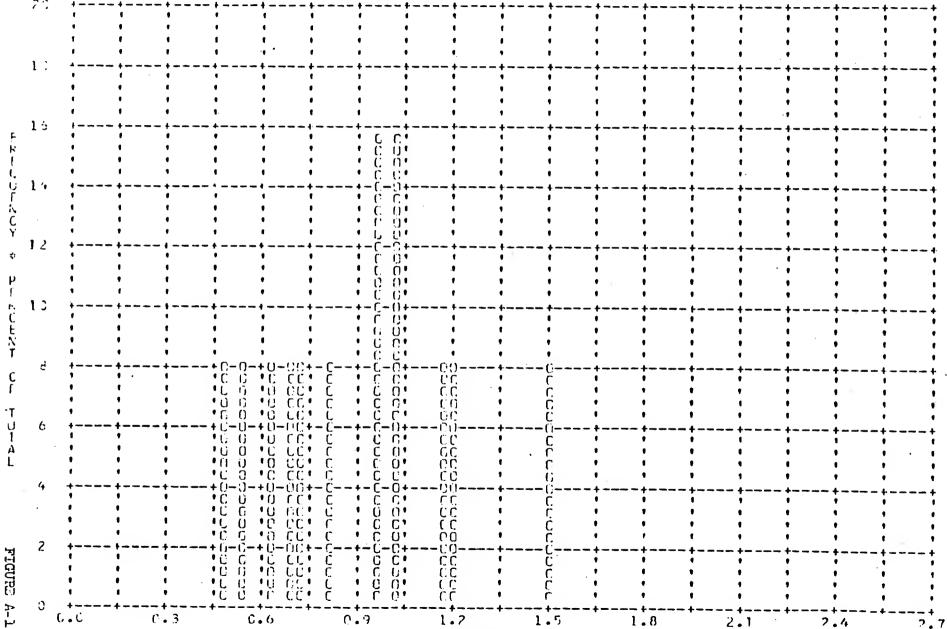
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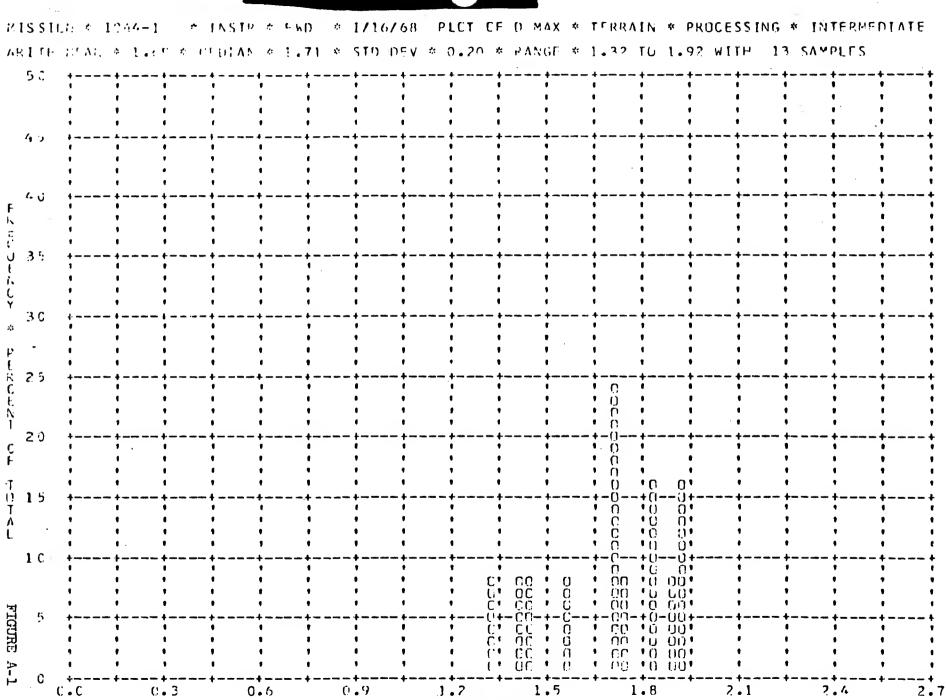
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SECTION A

APPENDIX

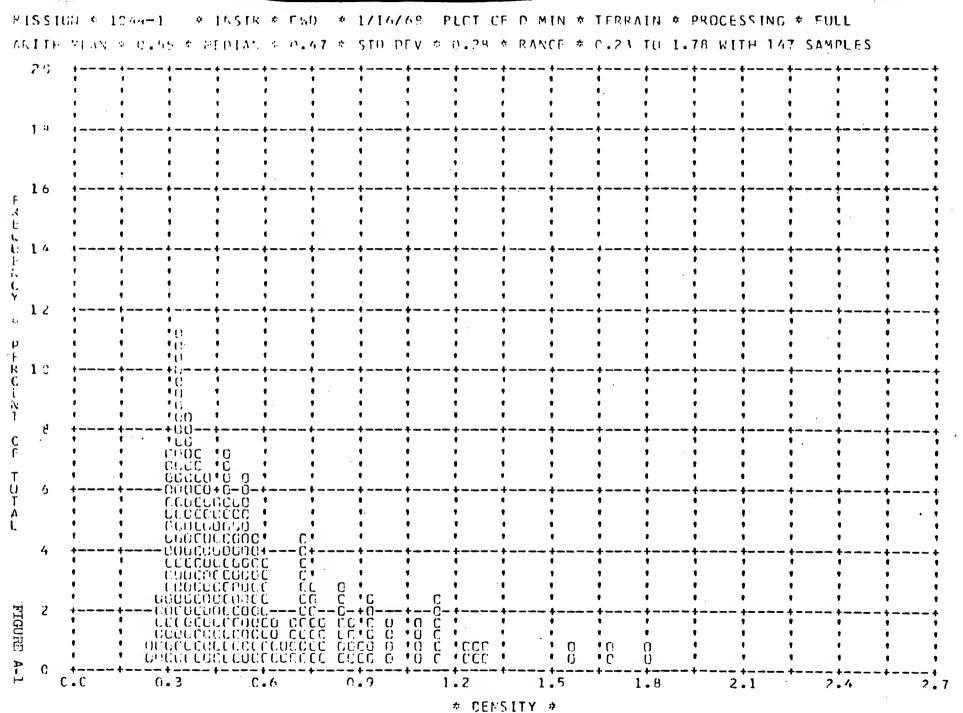




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TOP SHORET C

□ INSTR & FWO ★ 1/16/58 PLCT OF D MAX ★ CLOUD ★ PROCESSING ★ INTERMEDIATE NISSIN # 1044-1 ARTIF HEAD & 2.07 & MODIAN & 2.09 * SID DEV * 0.25 * RANGE * 1.58 TO 2.44 WITH 13 SAMPLES 1 16 0 * 0. 14 n • **n**• 0. 7 0. 0.1 12 0 • 0.1 **n** • n · n. R 10 0 4 (11 ŋ ı 0 1 0 1 11 . C O יח מיט טי กาก Ü ñü ים כֿ ם O O n • n U U 0 600 U. n• n Ö . U O 0 0 0 0 0 1) • n 6 0 4 O 0 0 0 0 n n Ô O O 0 0 0 0 0 0 0 0 1 บับกกับ 0 0(J 0 10 0 ' 00000 U O () 0 0 -n+-n-0 0.0.0 0.0 Ö n • n O U 0 0 0 0 Ü ÜÜ 0 0 0 0 **n** • n n 0 0 0 0 1 **n** • 0 FIGURE 0 • UU 0 0 0 0 0 () 1 () (i U D U 00000 J. U 0 0 0 0 00000 0 0 0 **n** • n 0 0000 (.3 1.2 C.C 0.6 0.9 . 1.8 2.1 2.4 2.7 * CENSITY *

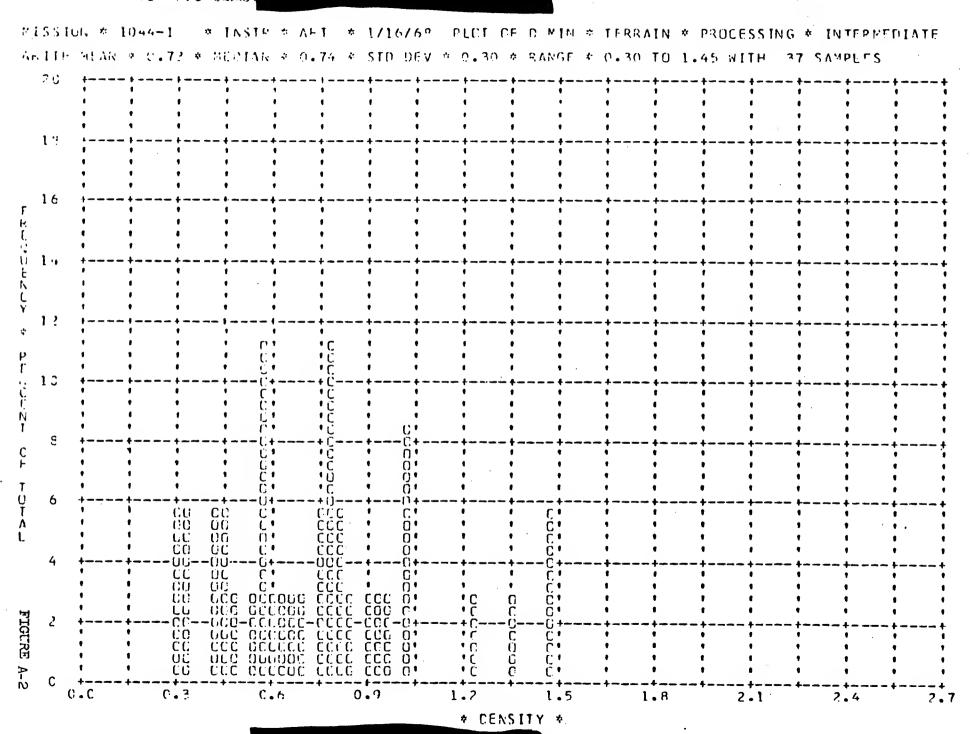


\$188365 # 1944-1 | #14878 # 960 # 1716768 PLOT UP D MAX # TERRAIN # PROCESSING # FHEE ANTIH MAN & 1.40 # MEDIAN & 1.57 # STO DEV # 0.40 # RANGE # 0.47 TO 2.36 WITH 147 SAMPLES 10 0 ' UM 0.0000 0 000001 0.0 000 0 00000 0.0 cco c ccoce. 0.0 000-0-00000+---0+0 100 CERTPORTO 0010 aca accennate quiu 00 nen edennosia ruio OO *CO 000 00000000 0000 00 0.000 +00-000-000000+0-00000--00--0-000--0-*CC 000 000000010 0000 CO \mathbf{u} \mathbf{u} *CÉ 000 000000010 0000 NU 0 000 0. 1000000 COCCCODICOODCODO DODUCOR CO U. FIGURE C'EGEGG CCCGOOM!CARDQCUUQQ DUOQCAO 00 00 (000 0 00 (000 0 COCCURCOCOCCOGRATION DE COCCURA DE COCURA DE COCURA DE COCCURA DE COCURA DE COCCURA DE COCCURA DE COCCURA DE COCCURA DE COCURA DE COCURA DE COCURA DE COCURA DE COCURA DE COCURA DE COCURA DE COCURA D * a pag nonuuuo Danuuopunn neg n* 0.0 C.3 0.9 0.6 1.5 1.8 2.1 7.4 2.7 MISSILL # 1044-1

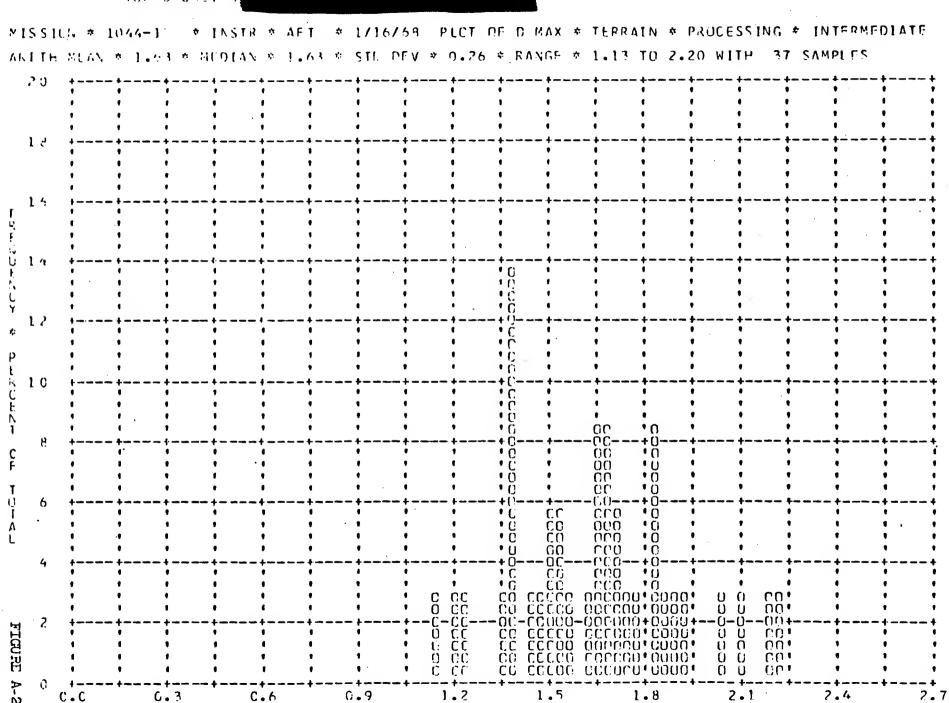
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TUP SECRET

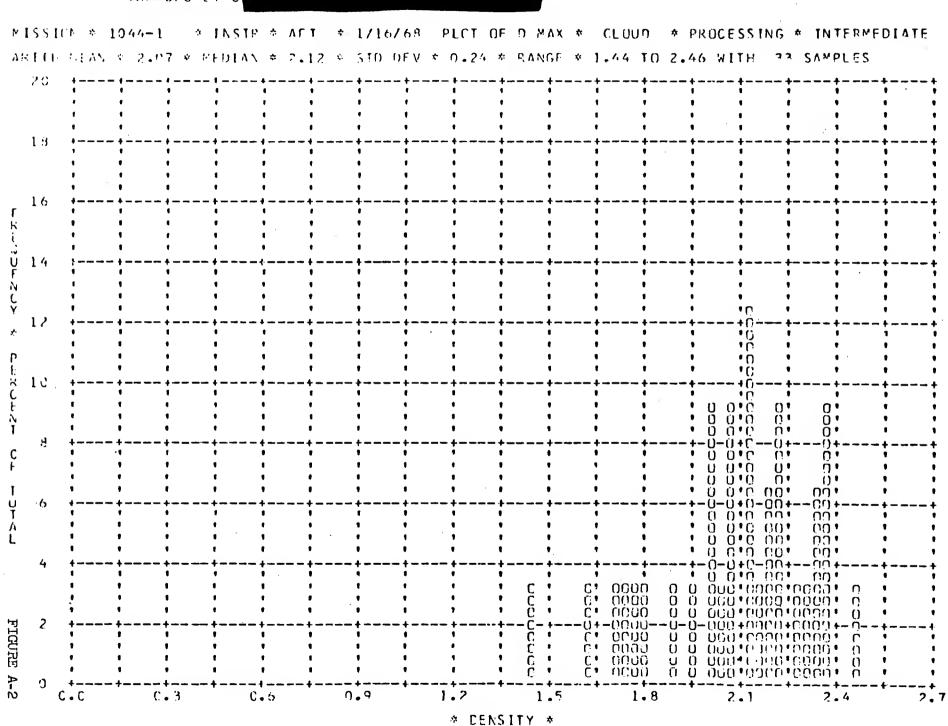


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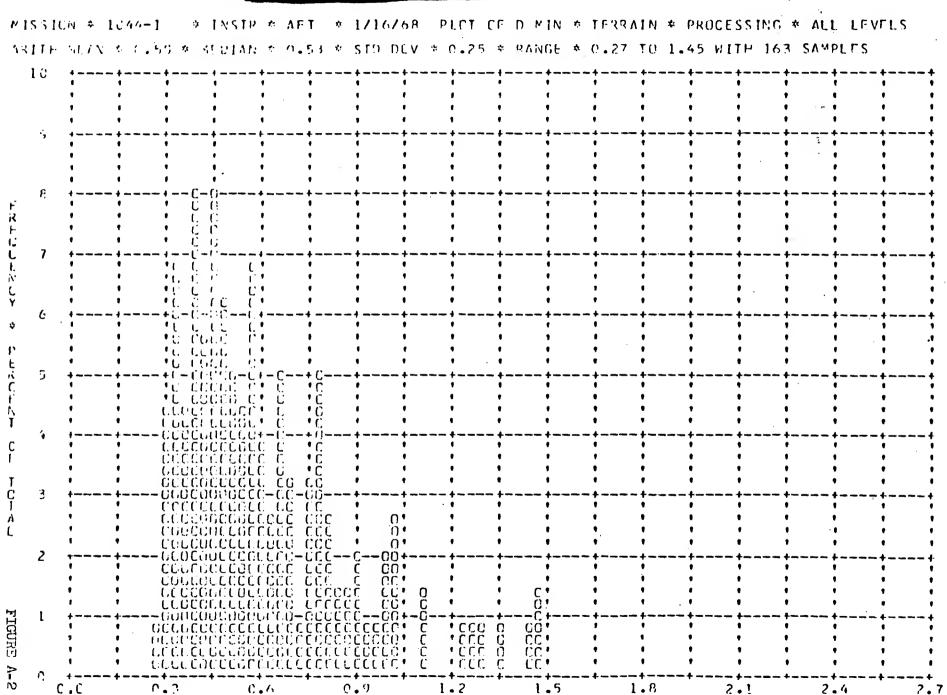
TUP SECRET C

MISSIUN # 1044-1 * INSTE * AFT * 1/16/63 PLCT OF D MAX * TERRAIN * PROCESSING * FULL ARITH MEAN # 1.55 # MEDIAN # 1.54 # STD DEV # 0.36 # MANGE # 0.76 TO 2.41 WITH 126 SAMPLES 10 UU 56 00 ቦበ 00·očč 0 ' 00 ' nn. U-CC-+UCU-O--C-+-CO-+-UÚ-+ 0 1 00 1 00 י פפר כ G GC *00C C 0 1 00 1 00 1 1000 č CC00 00 0 00 0 0 00 1000 0000 0000 00 00 0 --CN-CC-+DCC-C-OUCC-0N-O-O-OO-O 00 00 1000 0 0000 00 0 00 0 0 ' 0000 60 0000000000 CCCCCCCCCCCCCCCCCOMER COMMENCATION OF OUTO FIGURE *** 0 * 0000 U0 0000000000 00 0000 * 0 0* £00000000-4-0-0000000000-00-00-0-0-0-0-1000 0000000 A-2 0.9 1.2 1.8 2.1 C.C 0.3 C.6 2.4 2.7

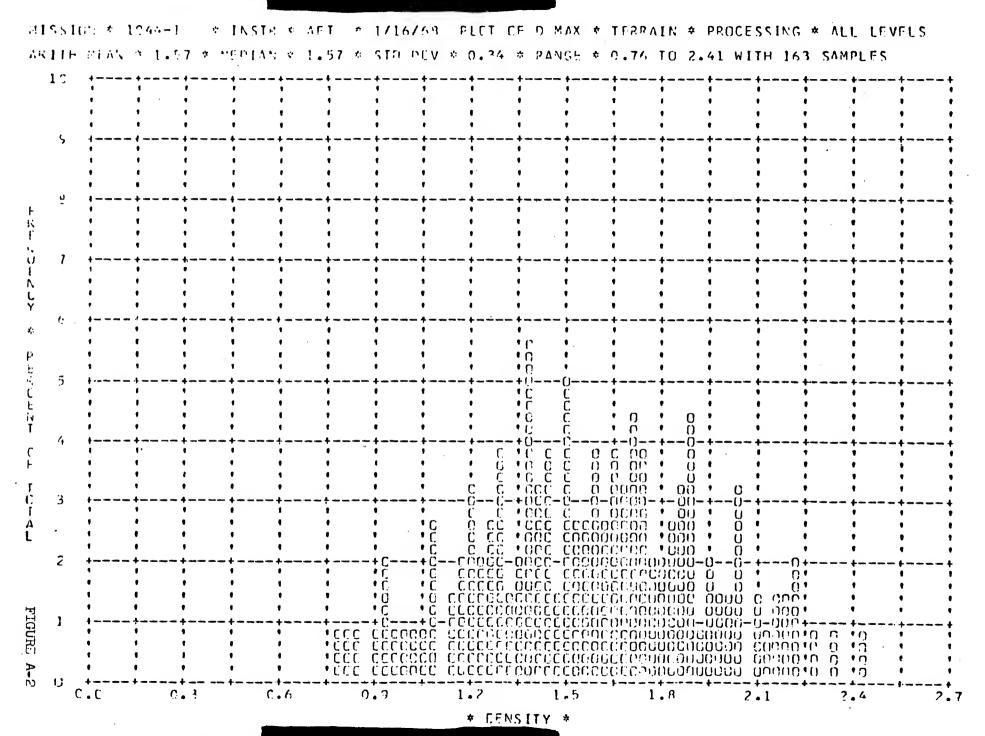
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TUP-SLERET



MISSION # 1044-1

10

FIGURE

F

C.C

ARITH MIAN # 4.09 > MEMIAN # 2.15 * STD DEV # 0.35 * RANGE * 0.32 TO 2.47 WITH 137 SAMPLES

* INSTR * AFT * 1/16/68 FECT OF D MAX * CLOUD * PROCESSING * ALL LEVELS

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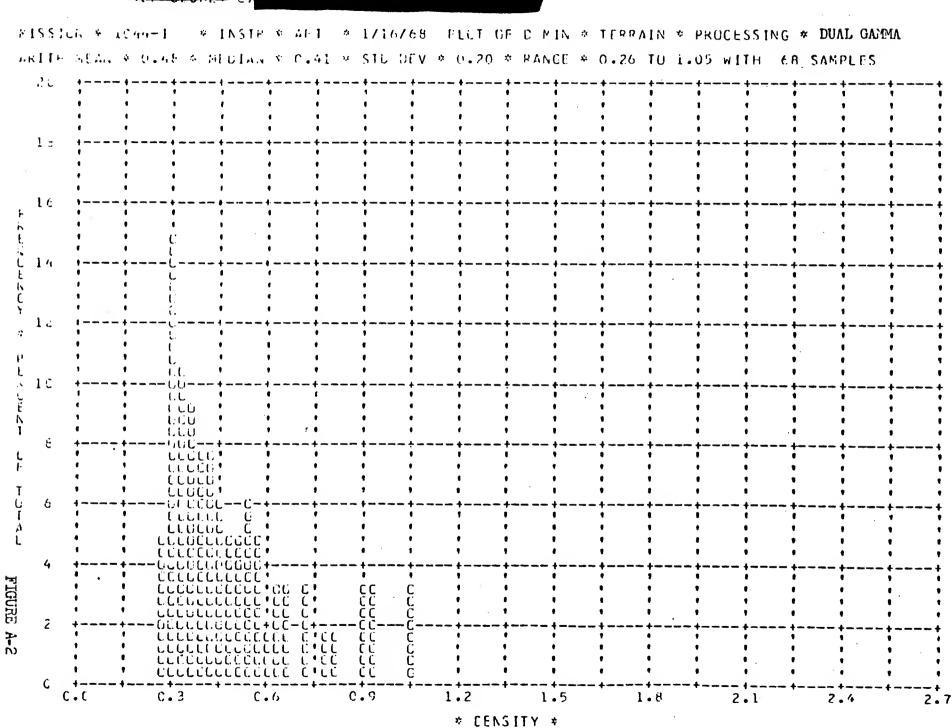
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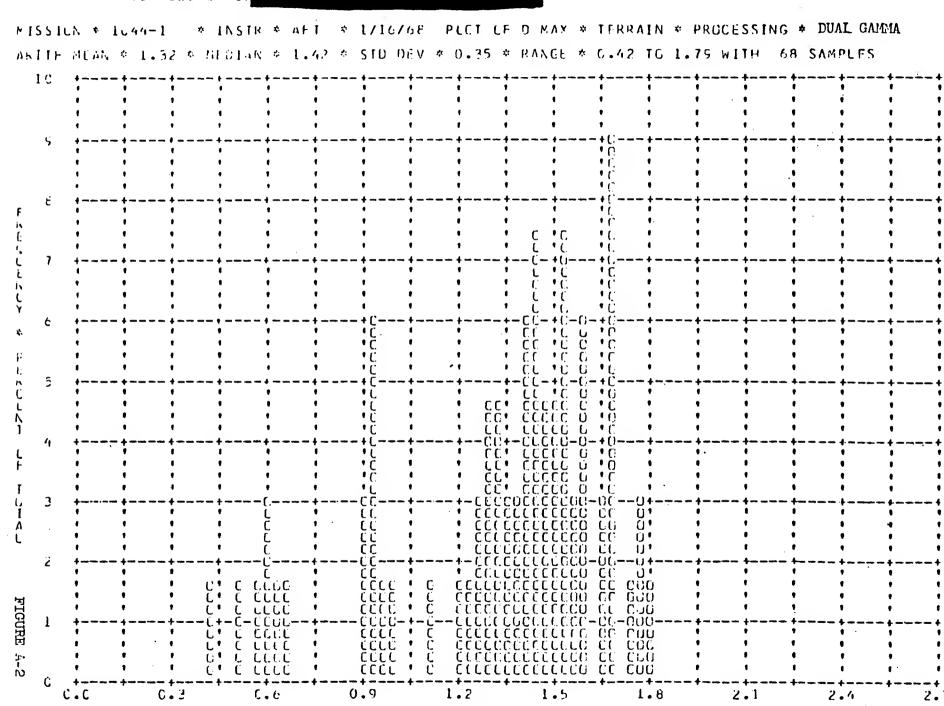
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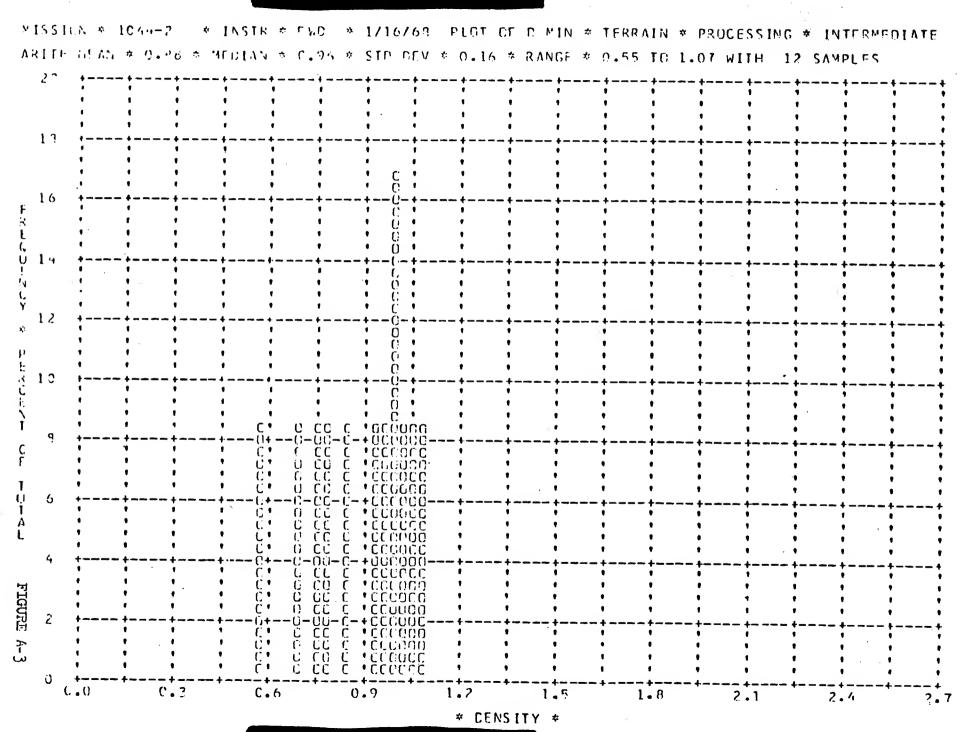
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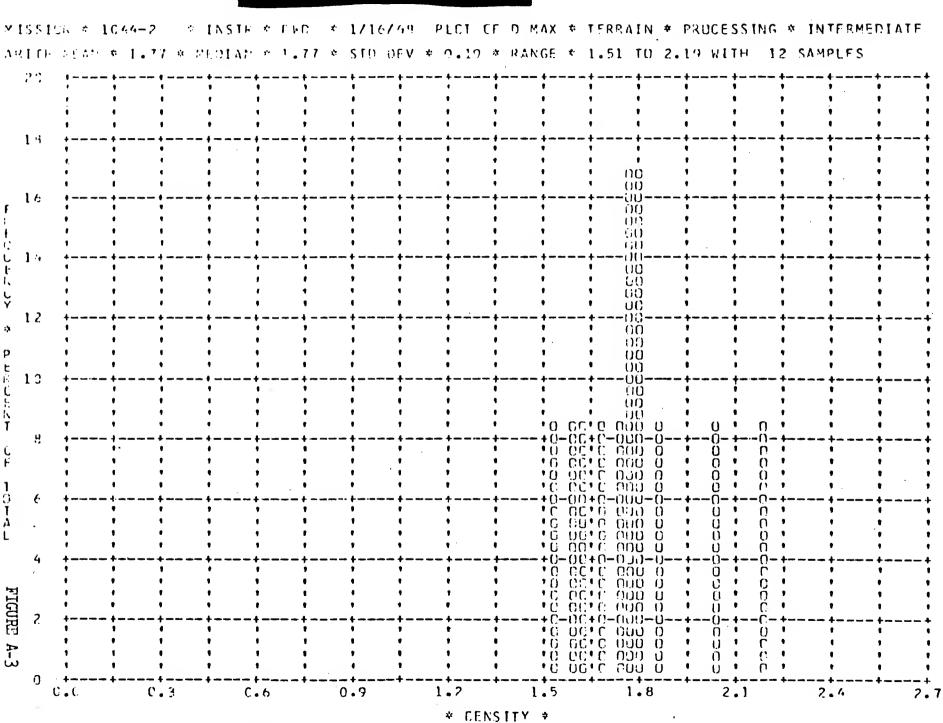
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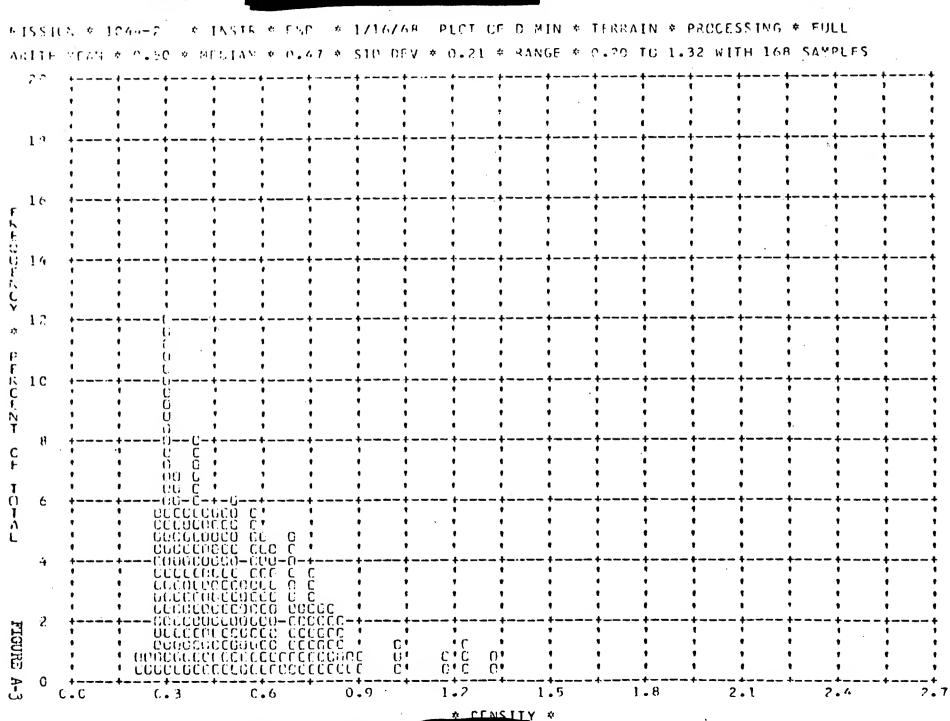


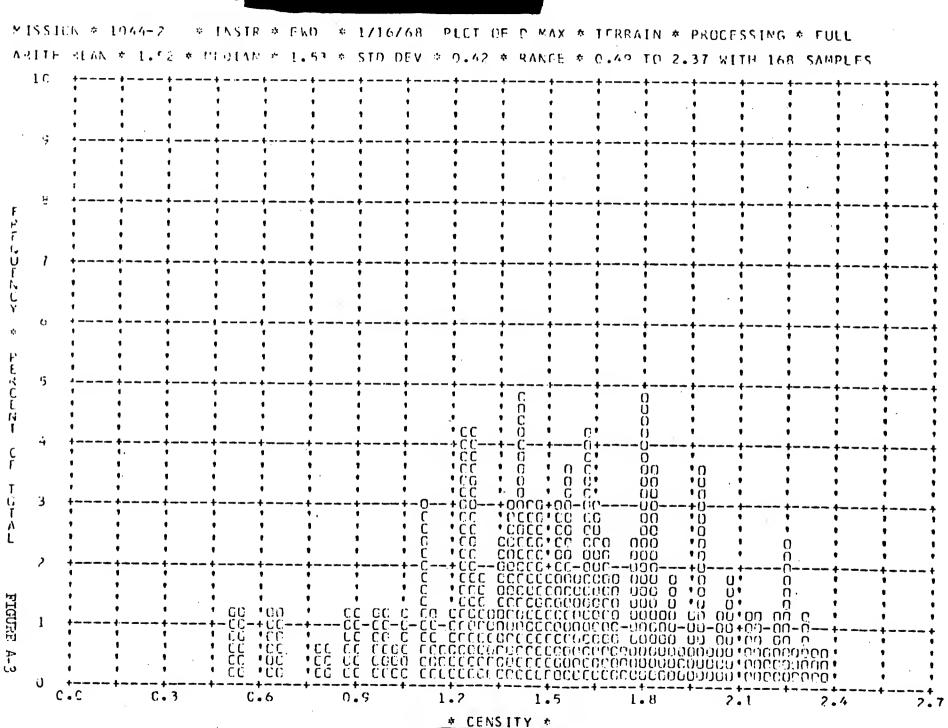
-TUP SECHET C

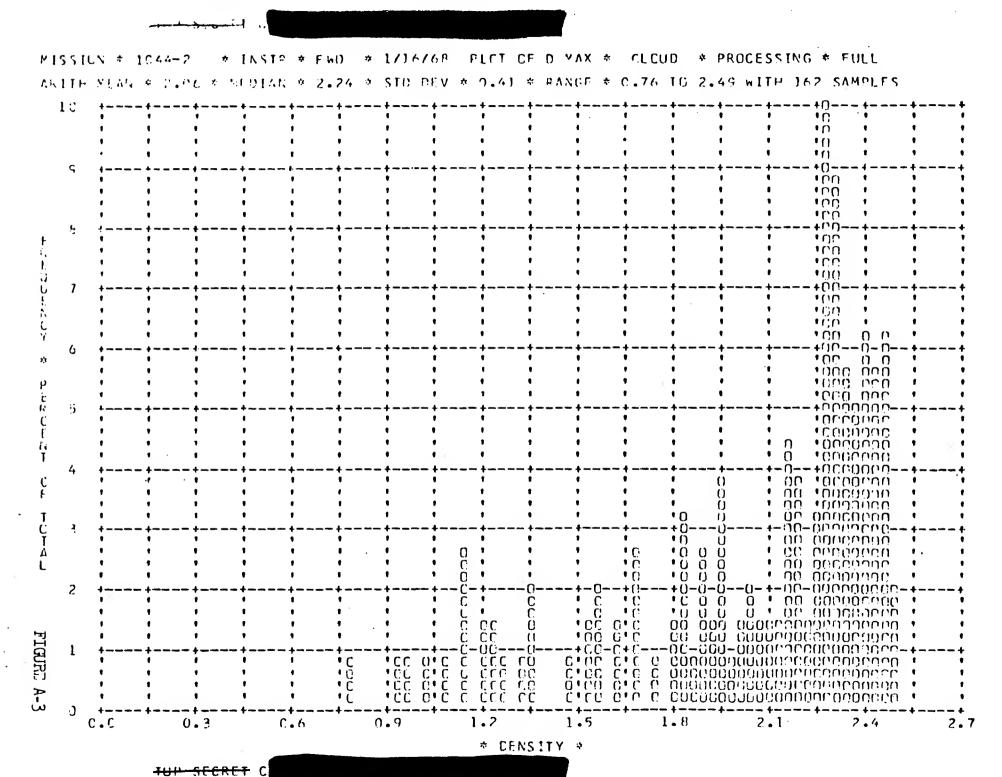


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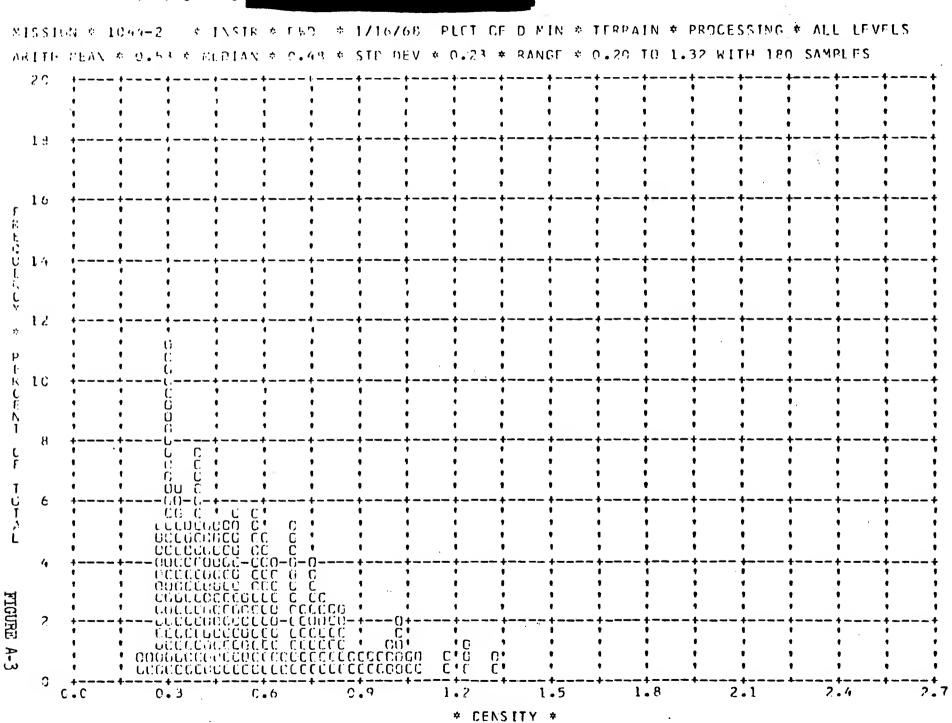
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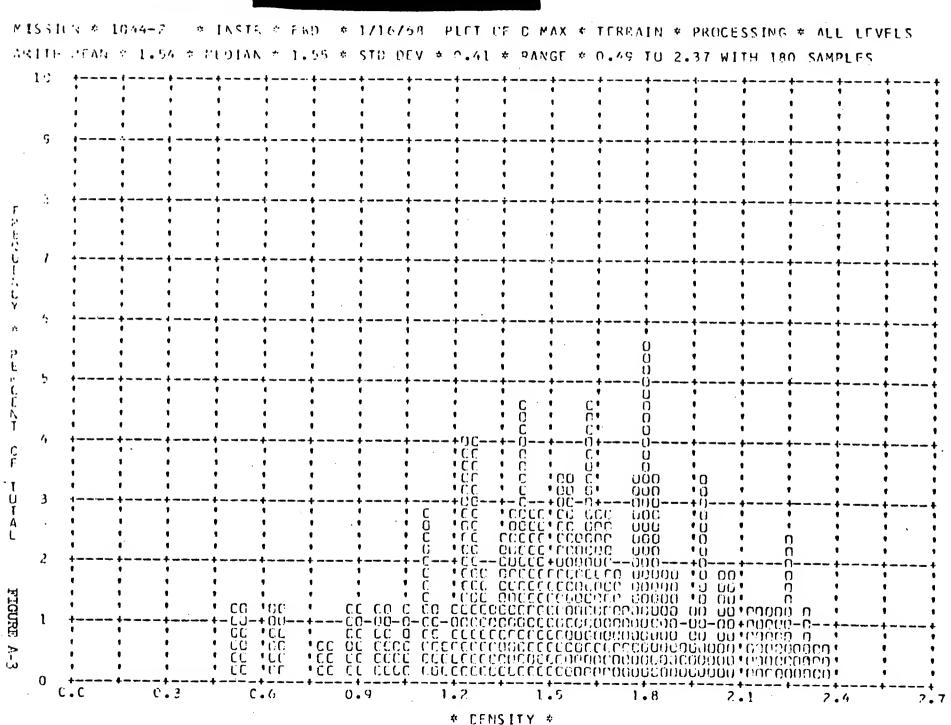




TOP SECRET. C



UP SECRET C



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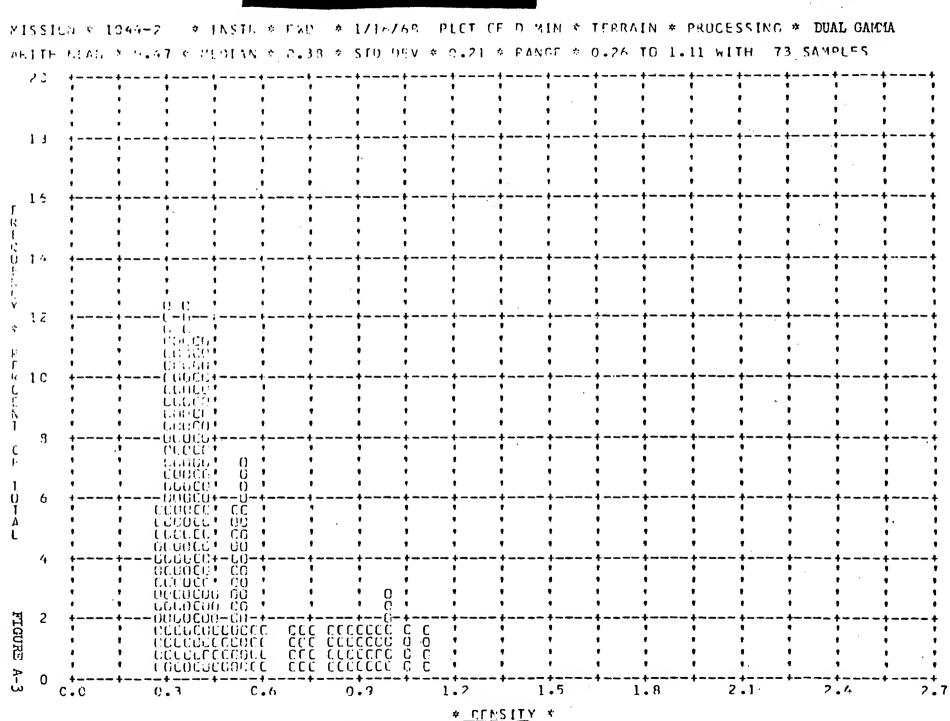
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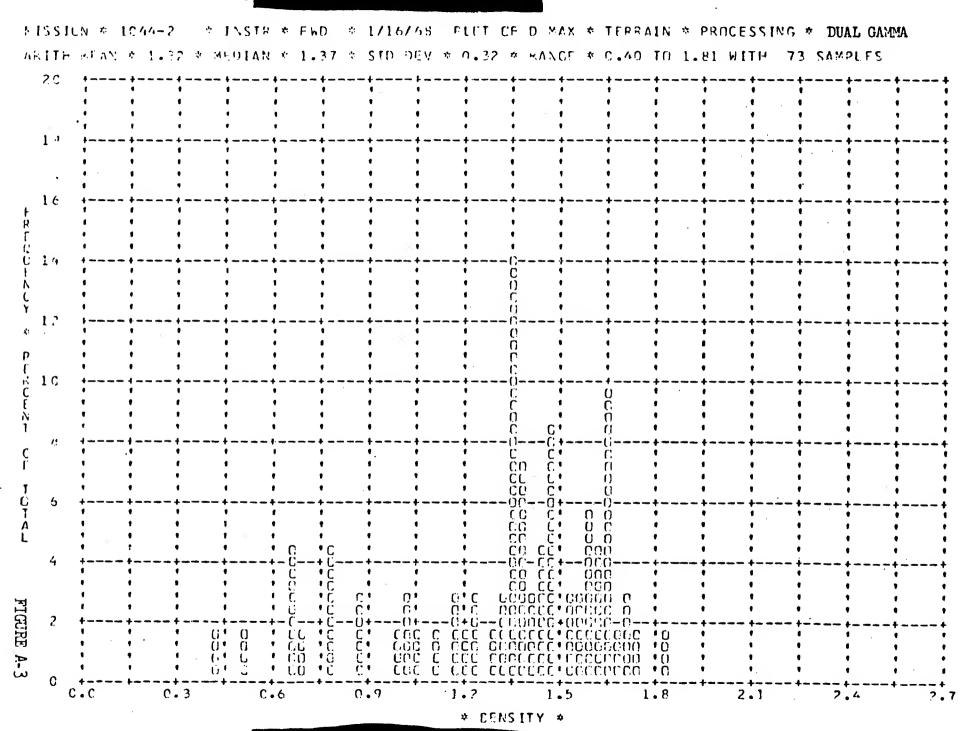
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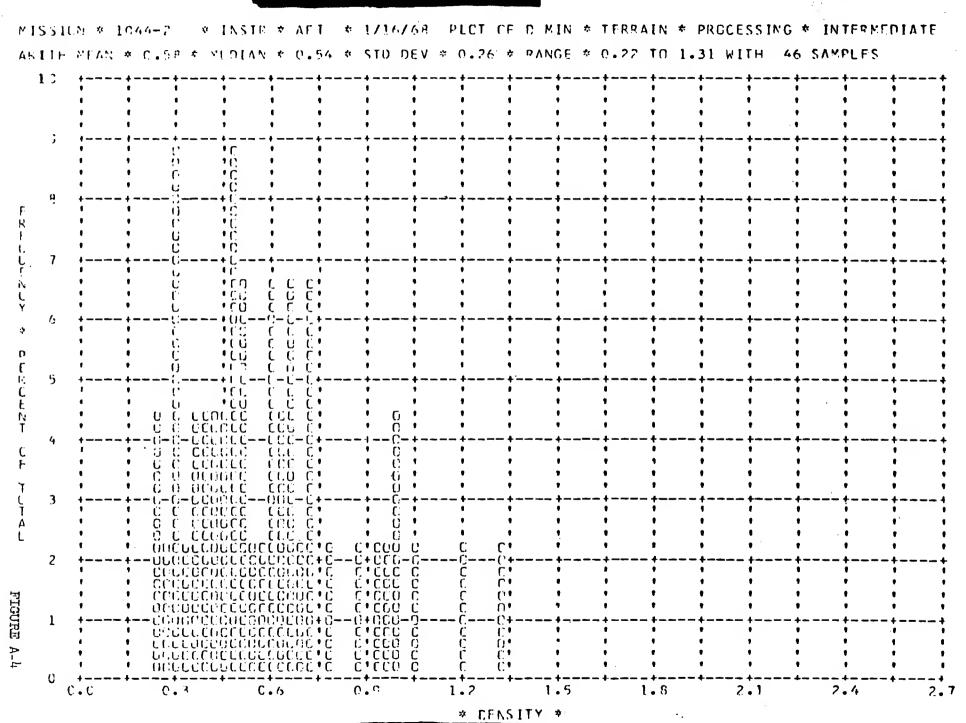


TOP SECKET-C

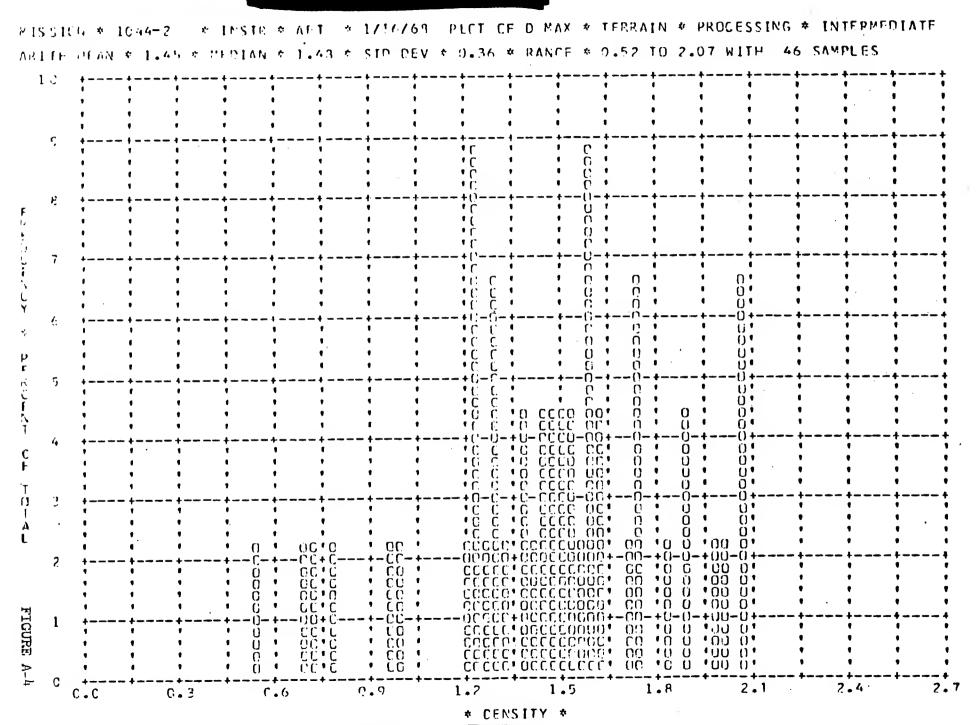


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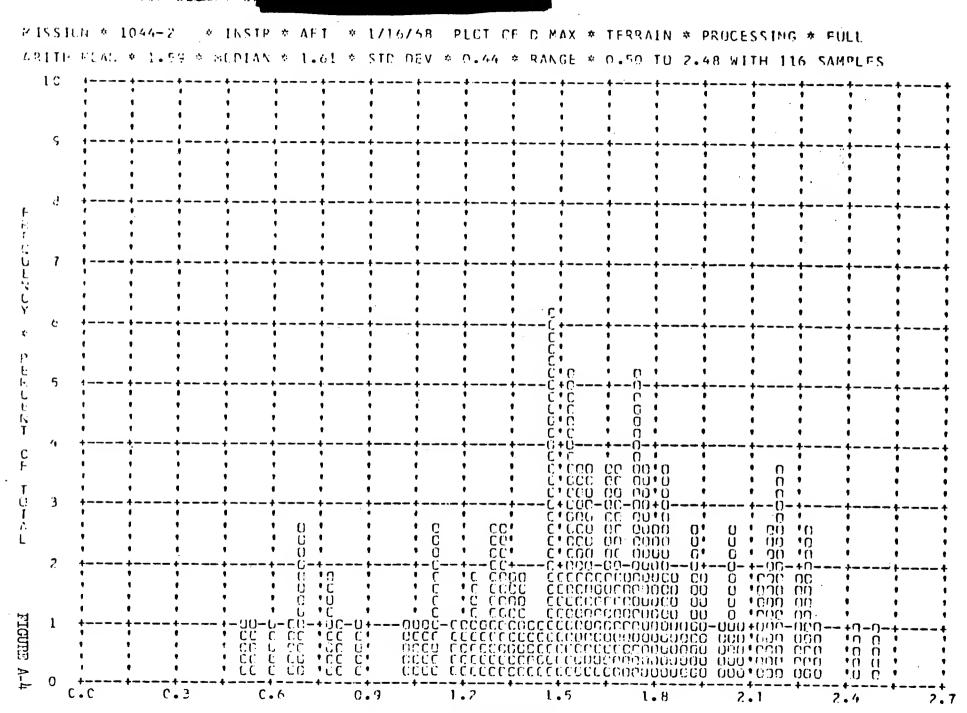
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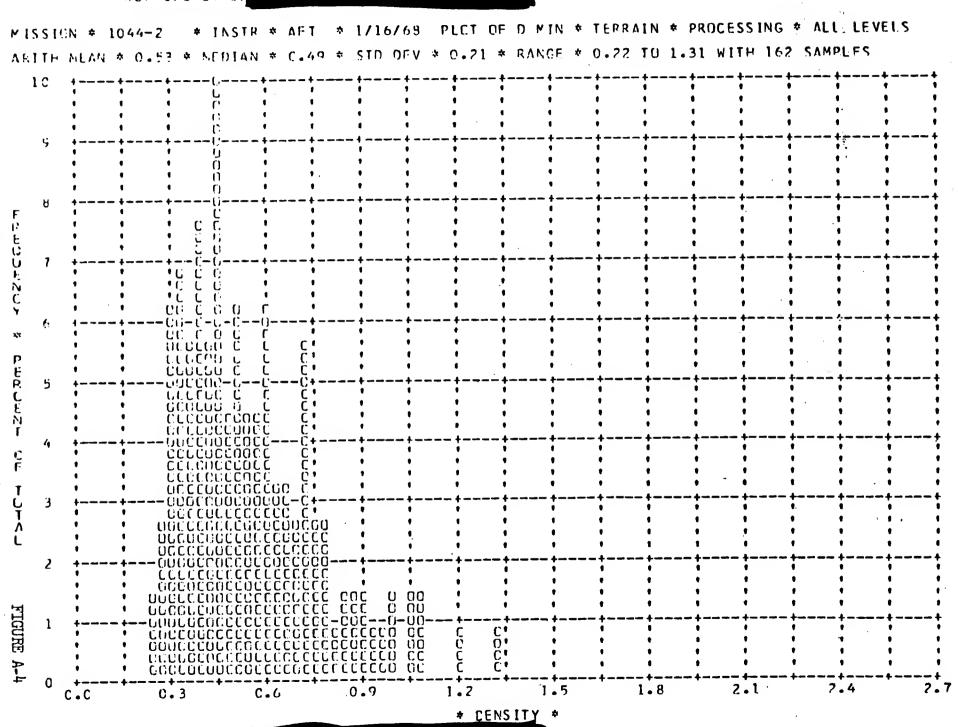
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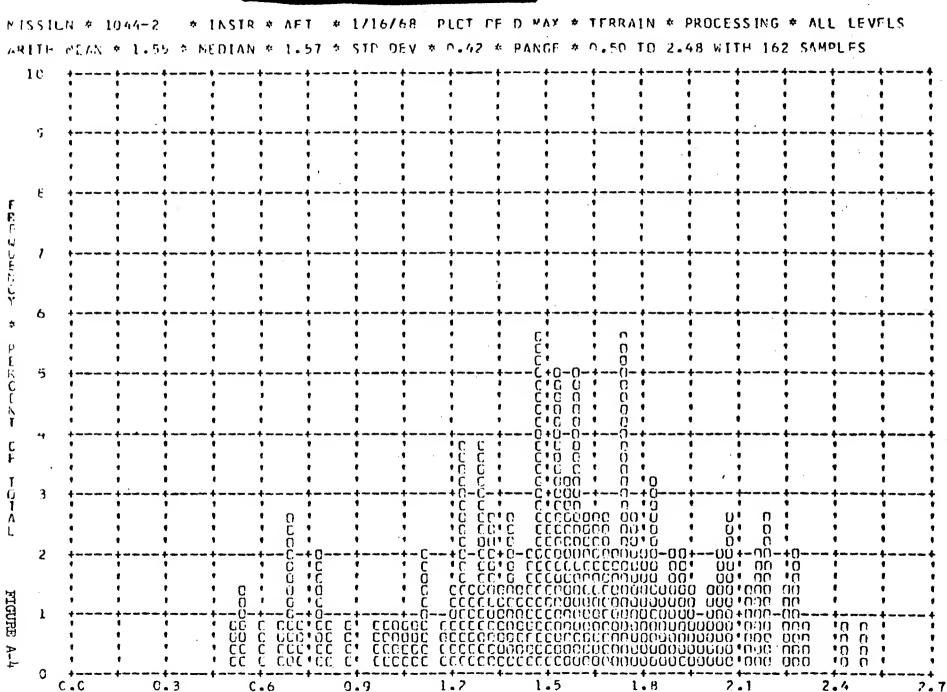


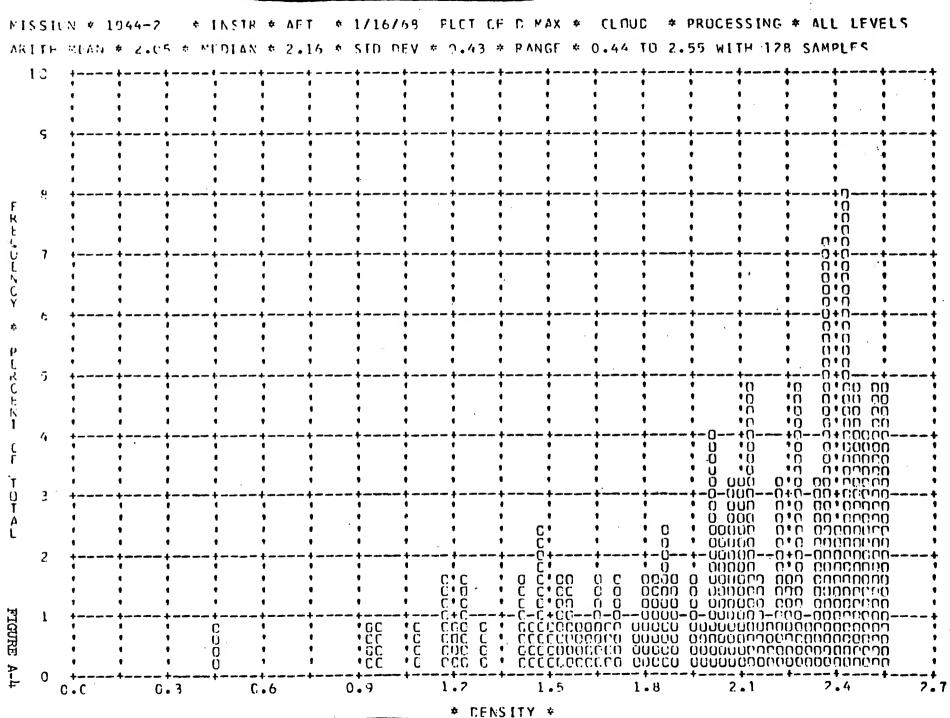
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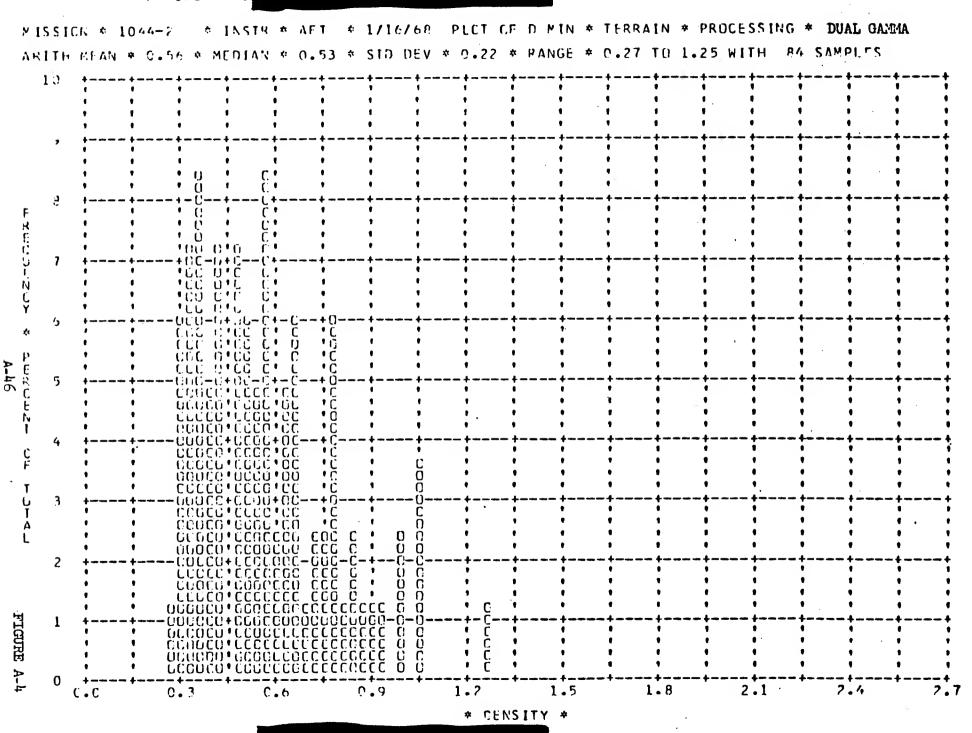
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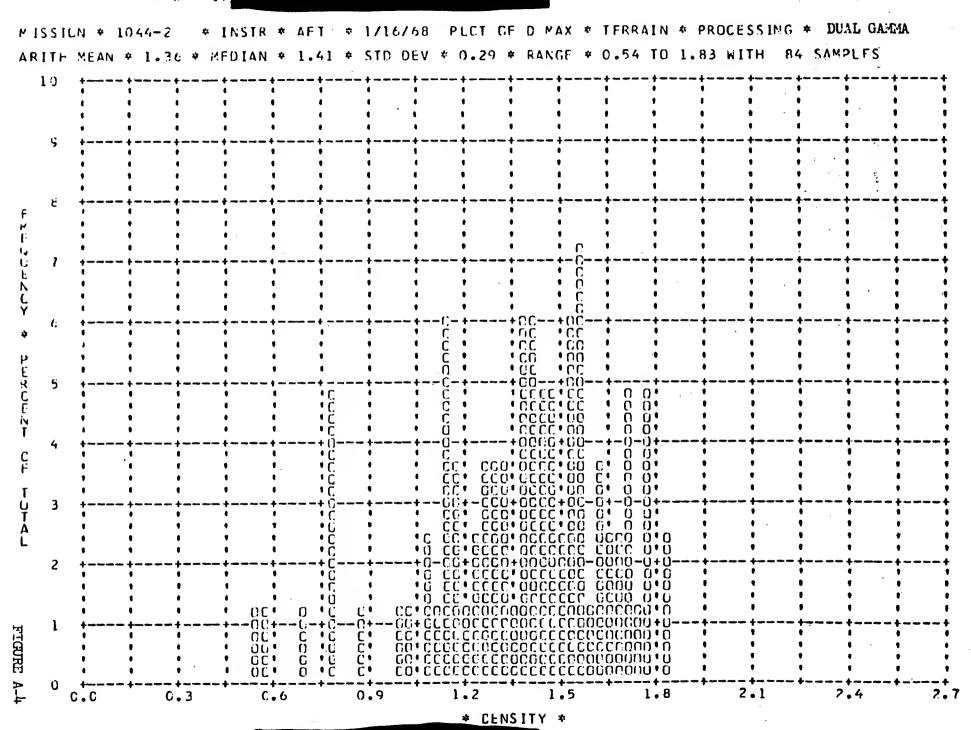
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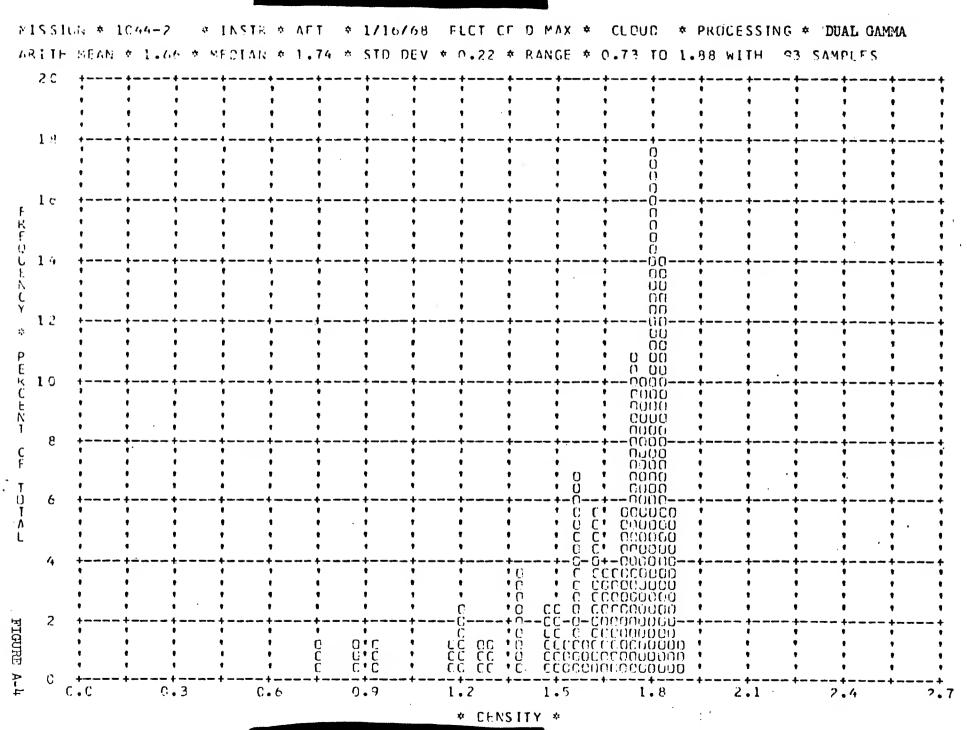












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